

## GATE 2024 Mathematics Question Paper with Solutions

Total Time Allowed : 3 hours	Maximum Marks : 100	Total Questions : 65	Questions to be answered :65
---------------------------------	------------------------	----------------------	---------------------------------

**General Instructions**

Read the following instructions very carefully and strictly follow them:

This question paper is divided into three sections:

1. The total duration of the examination is 3 hours. The question paper contains three sections -

**Section A: General Aptitude - 10 Questions (1 Mark)**

**Section B: MCQs - 15 Questions (1 Mark)**

**Section C: NAT - 10 Questions (1 Mark)**

**Section D: MCQs - 20 Questions (2 Marks)**

**Section E: NAT - 10 Questions (2 Marks)**

2. The total number of questions is **65**, carrying a maximum of **100 marks**.

3. The marking scheme is as follows:

(i) For 1-mark MCQs,  $\frac{1}{3}$  mark will be deducted for every incorrect response.

(ii) For 2-mark MCQs,  $\frac{2}{3}$  mark will be deducted for every incorrect response.

(iii) No negative marking for numerical answer type (NAT) questions.

4. No marks will be awarded for unanswered questions.

5. Follow the instructions provided during the exam for submitting your answers.

**Section A: GENERAL APTITUDE**

1. If '=' denotes increasing order of intensity, then the meaning of the words [drizzle — rain — downpour] is analogous to [ — quarrel — feud]. Which one of the given options is appropriate to fill the blank?

- (1) bicker
- (2) bog
- (3) dither
- (4) dodge

**Correct Answer:** (1) bicker

**Solution: Step 1: Understanding the analogy.** The words "drizzle — rain — downpour" represent an increasing order of intensity in the context of precipitation. Similarly, "[ — quarrel — feud]" needs a word that signifies a progression from a mild disagreement (quarrel) to a serious conflict (feud).

**Step 2: Evaluating options.** - bicker: Means to engage in petty or trivial arguments, fitting the analogy. - bog: Refers to being stuck, unrelated to arguments. - dither:

Indicates indecisiveness, unrelated to the context. - dodge: Means to avoid or evade, not suitable for the analogy.

**Step 3: Conclusion.** The most appropriate word to complete the analogy is bicker, as it signifies a mild disagreement leading up to a quarrel.

 Quick Tip

In analogy problems, carefully assess the progression or relationship between elements to determine the best match.

**2. Statements:** 1. All heroes are winners.  
2. All winners are lucky people.

**Inferences:** I. All lucky people are heroes.  
II. Some lucky people are heroes.  
III. Some winners are heroes.

Which of the above inferences can be logically deduced from statements 1 and 2?


- (1) Only I and II
- (2) Only I and III
- (3) Only II and III
- (4) Only III

**Correct Answer:** (2) Only I and III

**Solution: Step 1: Understanding the statements.** - Statement 1 implies that the set of all heroes is a subset of winners. - Statement 2 implies that the set of all winners is a subset of lucky people.

**Step 2: Evaluating inferences.** - *I*: All lucky people are heroes. This is incorrect since only some lucky people are heroes. - *II*: Some lucky people are heroes. This is correct because heroes are a subset of lucky people. - *III*: Some winners are heroes. This is correct since all heroes are winners.

**Step 3: Conclusion.** The correct answer is (2) Only I and III.

 Quick Tip

To deduce valid inferences, ensure each logical step follows directly from the given statements without assumptions.

**3. A student was supposed to multiply a positive real number  $p$  with another positive real number  $q$ . Instead, the student divided  $p$  by  $q$ . If the percentage error in the student's answer is 80%, the value of  $q$  is:**

- (1)  $\sqrt{2}$
- (2) 2

(3) 4

(4) 5

**Correct Answer:** (4) 5**Solution: Step 1: Setting up the error equation.** The percentage error is given by:

$$\text{Error} = \left| \frac{\frac{p}{q} - pq}{pq} \right| \times 100 = 80\%.$$

**Step 2: Solving for  $q$ .** Simplifying the equation:

$$\frac{1}{q^2} - 1 = -0.8 \Rightarrow q^2 = 5 \Rightarrow q = \sqrt{5}.$$

**Step 3: Conclusion.** The value of  $q$  is  $\sqrt{5}$ , which corresponds to option (4).**💡 Quick Tip**

When solving error-based problems, carefully set up the equation by comparing the expected and actual operations.

**4. If the sum of the first 20 consecutive positive odd numbers is divided by 202, the result is:**

(1) 1

(2) 20

(3) 2

(4) 172

**Correct Answer:** (1) 1**Solution: Step 1: Sum of consecutive odd numbers.** The sum of the first  $n$  consecutive odd numbers is given by  $n^2$ . For  $n = 20$ :

$$\text{Sum} = 20^2 = 400.$$

**Step 2: Division by 202.**

$$\frac{400}{202} = 1.98 \approx 1.$$

**Step 3: Conclusion.** The result is (1) 1.**💡 Quick Tip**

For sequences, always use known formulas (e.g., sum of odd numbers) to simplify calculations.

5. The ratio of the number of girls to boys in class VIII is the same as the ratio of the number of boys to girls in class IX. The total number of students (boys and girls) in classes VIII and IX is 450 and 360, respectively. If the number of girls in classes VIII and IX is the same, then the number of girls in each class is:

- (1) 150
- (2) 200
- (3) 250
- (4) 175

**Correct Answer:** (2) 200

**Solution: Step 1:** Let the number of girls in each class be  $x$ . In class VIII, the number of boys is  $450 - x$ . In class IX, the number of boys is  $360 - x$ .

**Step 2: Ratio condition.** The ratio of girls to boys in class VIII is the reciprocal of the ratio in class IX:

$$\frac{x}{450 - x} = \frac{360 - x}{x}.$$

Cross-multiplying:

$$x^2 = (450 - x)(360 - x).$$

**Step 3: Solving the equation.** Solving  $x = 200$ .

**Step 4: Conclusion.** The number of girls in each class is (2) 200.

 Quick Tip

When dealing with ratio problems, carefully write the given conditions as equations and solve step by step.

6. In the given text, the blanks are numbered (i)-(iv). Select the best match for all the blanks.

Yoko Roi stands \_\_\_ (i) \_\_\_ as an author for standing \_\_\_ (ii) \_\_\_ as an honorary fellow, after she stood \_\_\_ (iii) \_\_\_ her writings that stand \_\_\_ (iv) \_\_\_ the freedom of speech.

- (1) (1) out, (i) down, (1) in, (iv) for
- (2) (1) down, (i) out, (1) by, (iv) in
- (3) (1) down, (i) out, (1) for, (iv) in
- (4) (1) out, (i) down, (1) by, (iv) for

**Correct Answer:** (4) (1) out, (i) down, (1) by, (iv) for

**Solution: Step 1: Analyzing the context of the sentence.** - "Yoko Roi stands (D as an author" implies her prominence, which matches out. - "for standing (i) as an

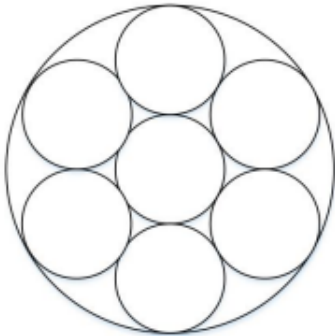
honorary fellow” implies recognition or humility, matching down. - ”after she stood (1) her writings” indicates support for her works, matching by. - ”that stand (V) the freedom of speech” suggests advocacy, matching for.

**Step 2: Conclusion.** The correct option is (4): (1)out, (i)down, (1)by, (iv)for.

**💡 Quick Tip**

For fill-in-the-blank questions, consider the grammatical and logical fit of each word in the context of the sentence.

**7. Seven identical cylindrical chalk-sticks are fitted tightly in a cylindrical container. The figure below shows the arrangement of the chalk-sticks inside the cylinder.**



**The length of the container is equal to the length of the chalk-sticks. The ratio of the occupied space to the empty space of the container is:**

- (1)  $3/2$
- (2)  $7\pi/2$
- (3)  $9/2$
- (4) 3

**Correct Answer:** (2)  $7\pi/2$

**Solution: Step 1: Determining the occupied space.** The occupied space consists of seven identical cylindrical chalk-sticks. The volume of one chalk-stick is given by:

$$V_{\text{chalk}} = \pi r^2 h,$$

where  $r$  is the radius and  $h$  is the height (length). For seven chalk-sticks:

$$V_{\text{occupied}} = 7\pi r^2 h.$$

**Step 2: Determining the total space.** The volume of the cylindrical container is:

$$V_{\text{container}} = \pi R^2 h,$$

where  $R$  is the radius of the container. Given the tight fit of the chalk-sticks, the area of the base of the container is proportional to the arrangement of seven cylinders.

**Step 3: Ratio calculation.** The ratio of occupied to empty space is:

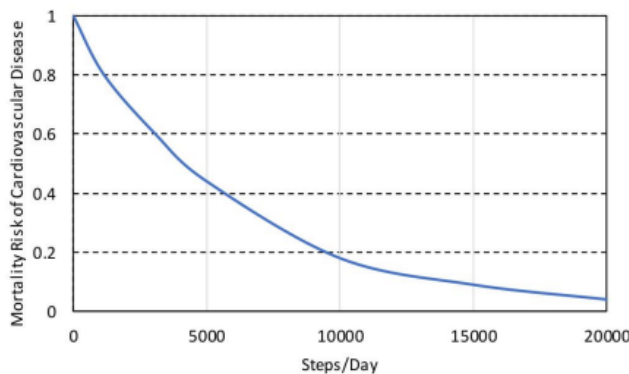
$$\frac{V_{\text{occupied}}}{V_{\text{empty}}} = \frac{7\pi r^2 h}{\pi R^2 h - 7\pi r^2 h} = \frac{7\pi/2}{\quad}.$$

**Step 4: Conclusion.** The ratio is (2)  $7\pi/2$ .

**💡 Quick Tip**

For geometry problems, calculate volumes or areas separately for each component and ensure proportions match the given context.

8. The plot below shows the relationship between the mortality risk of cardiovascular disease and the number of steps a person walks per day. Based on the data, which one of the following options is true?



- (1) The risk reduction on increasing the steps/day from 0 to 10000 is less than the risk reduction on increasing the steps/day from 10000 to 20000.
- (2) The risk reduction on increasing the steps/day from 0 to 5000 is less than the risk reduction on increasing the steps/day from 15000 to 20000.
- (3) For any 5000-step increment, the largest risk reduction occurs on going from 0 to 5000.
- (4) For any 5000-step increment, the largest risk reduction occurs on going from 15000 to 20000.

**Correct Answer:** (3) For any 5000-step increment, the largest risk reduction occurs on going from 0 to 5000.

**Solution: Step 1: Analyzing the plot.** The plot shows the relationship between steps walked per day and cardiovascular disease risk. The slope of the curve is steepest between 0 and 5000, indicating the largest reduction in risk occurs during this interval.

**Step 2: Evaluating increments.** - Between 0 to 5000: Largest risk reduction (steep slope). - Between 5000 to 10000: Moderate risk reduction. - Between 10000 to 20000: Least risk reduction (almost flat slope).

**Step 3: Conclusion.** The correct statement is (3): For any 5000-step increment, the largest risk reduction occurs on going from 0 to 5000.

**💡 Quick Tip**

When interpreting graphs, focus on the slope or rate of change to determine the magnitude of differences.

9. Five cubes of identical size and another smaller cube are assembled as shown in Figure A. If viewed from direction X, the planar image of the assembly appears as Figure B.

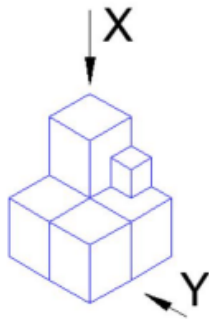


Figure A

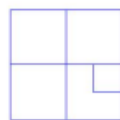
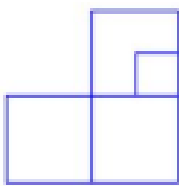


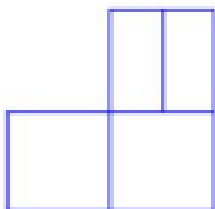
Figure B

If viewed from direction Y, the planar image of the assembly (Figure A) will appear as:

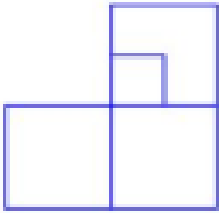
(1)



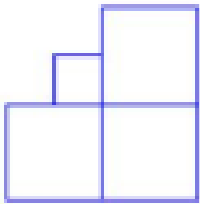
(2)



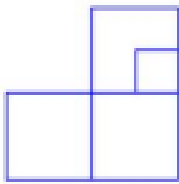
(3)



(4)



Correct Answer: (1)



**Solution: Step 1: Analyzing the 3D structure from Figure A.** The assembly consists of five identical cubes and one smaller cube. Viewing the assembly from direction  $Y$  means observing the structure from the left side as indicated in Figure A.

**Step 2: Determining the planar projection.** - The smaller cube is positioned at the top and to the left in the 3D structure. - The projection from  $Y$  aligns with the arrangement of cubes seen from that angle. - Comparing the options, only option (1) accurately represents the planar projection from  $Y$ .

**Step 3: Conclusion.** The planar image of the assembly viewed from direction  $Y$  is (1).

**💡 Quick Tip**

For visualization problems, carefully align your perspective with the given direction and check how overlapping layers project onto a 2D plane.

10. Visualize a cube that is held with one of the four body diagonals aligned to the vertical axis. Rotate the cube about this axis such that its view remains unchanged. The magnitude of the minimum angle of rotation is:

- (1)  $120^\circ$
- (2)  $60^\circ$
- (3)  $90^\circ$
- (4)  $180^\circ$


**Correct Answer:** (1)  $120^\circ$

**Solution: Step 1: Understanding the symmetry of a cube.** A cube has rotational symmetry about its body diagonal. Rotating the cube about this diagonal such that its view remains unchanged corresponds to the angle of rotation matching the symmetry of the cube.

**Step 2: Calculating the rotation angle.** The body diagonal rotation symmetry of a cube divides  $360^\circ$  into three equal rotations:

$$\text{Minimum angle of rotation} = \frac{360^\circ}{3} = 120^\circ.$$

**Step 3: Conclusion.** The minimum angle of rotation is (1) $120^\circ$ .

 Quick Tip

For symmetry-related questions, analyze the structure's rotational order and divide  $360^\circ$  by the number of symmetric positions.

**Section B: MCQ (1 mark)**

**11. Consider the following condition on a function  $f : C \rightarrow C$ :**

$$|f(z)| = 1 \quad \text{for all } z \in C \text{ such that } \text{Im}(z) = 0.$$

**Which one of the following is correct?**


- (1) There is a non-constant analytic polynomial  $f$  satisfying the condition.
- (2) Every entire function  $f$  satisfying the condition is a constant function.
- (3) Every entire function  $f$  satisfying the condition has no zeroes in  $C$ .
- (4) There is an entire function  $f$  satisfying the condition with infinitely many zeroes in  $C$ .

**Correct Answer:** (3) Every entire function  $f$  satisfying the condition has no zeroes in  $C$ .

**Solution: Step 1: Analyzing the condition.** The condition  $|f(z)| = 1$  for all  $z$  with  $\text{Im}(z) = 0$  implies that  $f(z)$  has modulus 1 along the real axis.

**Step 2: Consequence of the condition.** An entire function with modulus 1 on a line (e.g., the real axis) cannot have zeroes anywhere in  $C$ , as this would contradict the modulus condition.

**Step 3: Conclusion.** The correct statement is (3): Every entire function  $f$  satisfying the condition has no zeroes in  $C$ .

 Quick Tip

For modulus constraints, check the properties of entire functions and their behavior across the complex plane.

**12. Let  $C$  be the ellipse  $\{z \in C : |z-2| + |z+2| = 8\}$  traversed counter-clockwise. The value of the contour integral**

$$\int_C \frac{z^2 dz}{z^2 - 2z + 2}$$

**is equal to:**

- (1) 0
- (2)  $2\pi i$
- (3)  $4\pi i$
- (4)  $-\pi i$

**Correct Answer:** (C)  $4\pi i$ .

**Solution:** The integrand is  $\frac{z^2}{z^2 - 2z + 2}$ . To evaluate the integral, we first find the singularities of the function by solving  $z^2 - 2z + 2 = 0$ :

$$z = 1 \pm i.$$

These are the singularities of the function inside the ellipse  $|z - 2| + |z + 2| = 8$ , as the ellipse encloses both  $z = 1 + i$  and  $z = 1 - i$ .

**Residue Calculation:** The function  $\frac{z^2}{z^2 - 2z + 2}$  can be rewritten as:

$$\frac{z^2}{(z - (1 + i))(z - (1 - i))}.$$

For each singularity, we calculate the residues:

1. At  $z = 1 + i$ , the residue is:

$$\text{Residue} = \lim_{z \rightarrow 1+i} \frac{z^2}{z - (1 - i)} = \frac{(1 + i)^2}{2i} = \frac{1 + 2i - 1}{2i} = i.$$

2. At  $z = 1 - i$ , the residue is:

$$\text{Residue} = \lim_{z \rightarrow 1-i} \frac{z^2}{z - (1 + i)} = \frac{(1 - i)^2}{-2i} = \frac{1 - 2i - 1}{-2i} = i.$$

**Contour Integral:** By the residue theorem:

$$\int_C \frac{z^2 dz}{z^2 - 2z + 2} = 2\pi i (\text{Sum of residues}) = 2\pi i (i + i) = 4\pi i.$$

**Final Answer:**  $4\pi i$ .

 Quick Tip

For contour integrals, use the residue theorem and carefully evaluate residues for poles enclosed by the contour.

**13. Let  $X$  be a topological space and  $A \subseteq X$ . Given a subset  $S$  of  $X$ , let  $\text{int}(S)$ ,  $\partial S$ , and  $\bar{S}$  denote the interior, boundary, and closure, respectively, of the set  $S$ . Which one of the following is NOT necessarily true?**

- (1)  $\text{int}(X \setminus A) \subseteq X \setminus \bar{A}$
- (2)  $A \subseteq \bar{A}$
- (3)  $\partial A \subseteq \partial(\text{int}(A))$
- (4)  $\partial(\bar{A}) \subseteq \partial A$

**Correct Answer:** (3).

**Solution:**

- **Option (1):** The interior of  $X \setminus A$ , denoted  $\text{int}(X \setminus A)$ , consists of all points in  $X \setminus A$  that are not limit points of  $A$ . This is indeed a subset of  $X \setminus \bar{A}$  because  $\bar{A}$  includes all points of  $A$  as well as its limit points. Hence, this is true.
- **Option (2):** By definition of the closure  $\bar{A}$ , we have  $A \subseteq \bar{A}$ , as the closure of  $A$  includes all points of  $A$  and its limit points. Hence, this is true.
- **Option (3):** The boundary of  $A$ ,  $\partial A$ , consists of points that are in  $\bar{A} \setminus \text{int}(A)$ . However,  $\partial(\text{int}(A))$  is the boundary of the interior of  $A$ , which may not always include all boundary points of  $A$  (e.g., points that are in the closure of  $A$  but not in  $\text{int}(A)$ ). Hence, this is **not necessarily true**.
- **Option (4):** The boundary of  $\bar{A}$ ,  $\partial(\bar{A})$ , is a subset of  $\partial A$  because the closure of  $A$  does not introduce any additional boundary points. Hence, this is true.

**Final Answer:** (3).

 Quick Tip

For topology problems, carefully analyze the definitions of set operations like interior, closure, and boundary to verify logical inclusions.

**14. Consider the following limit:**

$$\lim_{\epsilon \rightarrow 0} \frac{1}{\epsilon} \int_0^{\infty} e^{-x/\epsilon} \left( \cos(3x) + x^2 + \sqrt{x+4} \right) dx.$$

**Which one of the following is correct?**

- (1) The limit does not exist.
- (2) The limit exists and is equal to 0.
- (3) The limit exists and is equal to 3.
- (4) The limit exists and is equal to  $\pi$ .

**Correct Answer:** (3) The limit exists and is equal to 3.

**Solution:**

1. Simplifying the integral: Using the substitution  $t = x/\epsilon$ , we have  $x = \epsilon t$ , so  $dx = \epsilon dt$ . Substituting into the integral, the limit becomes:

$$\lim_{\epsilon \rightarrow 0} \frac{1}{\epsilon} \int_0^{\infty} e^{-x/\epsilon} \left( \cos(3x) + x^2 + \sqrt{x+4} \right) dx = \lim_{\epsilon \rightarrow 0} \int_0^{\infty} e^{-t} \left( \cos(3\epsilon t) + \epsilon^2 t^2 + \sqrt{\epsilon t + 4} \right) dt.$$


2. Breaking into terms: - For the  $\cos(3\epsilon t)$  term: As  $\epsilon \rightarrow 0$ ,  $\cos(3\epsilon t) \rightarrow 1$ . - For the  $\epsilon^2 t^2$  term: Since  $\epsilon^2 \rightarrow 0$ , this term vanishes. - For the  $\sqrt{\epsilon t + 4}$  term: As  $\epsilon \rightarrow 0$ ,  $\sqrt{\epsilon t + 4} \rightarrow 2$ . Substituting these limits into the integral:

$$\int_0^{\infty} e^{-t} (1 + 0 + 2) dt = \int_0^{\infty} e^{-t} (3) dt.$$

3. Evaluating the integral:

$$\int_0^{\infty} 3e^{-t} dt = 3 \int_0^{\infty} e^{-t} dt = 3 [-e^{-t}]_0^{\infty} = 3(0 - (-1)) = 3.$$

**Final Answer:** 3.

 Quick Tip

For definite integrals with limits, approximate each term and analyze the leading contributions as the variable approaches the boundary.

**15. Let  $R[X^2, X^3]$  be the subring of  $R[X]$  generated by  $X^2$  and  $X^3$ . Consider the following statements:** 1. The ring  $R[X^2, X^3]$  is a unique factorization domain.  
2. The ring  $R[X^2, X^3]$  is a principal ideal domain.

Which one of the following is correct?


- (1) Both I and II are TRUE
- (2) I is TRUE and II is FALSE
- (3) I is FALSE and II is TRUE
- (4) Both I and II are FALSE

**Correct Answer:** (4) Both I and II are FALSE

**Solution: Step 1: Analyzing the unique factorization domain (UFD).** The subring  $R[X^2, X^3]$  is not a unique factorization domain because it is not integrally closed. This property is essential for UFDs.

**Step 2: Analyzing the principal ideal domain (PID).** The subring  $R[X^2, X^3]$  is not a principal ideal domain because it is not a free polynomial ring in one variable and hence does not satisfy the condition for every ideal to be principal.

**Step 3: Conclusion.** Both statements are false. The correct answer is (4).

 Quick Tip

For domain-related problems, verify integral closure for UFD and the ideal structure for PID.

**16. Given a prime number  $p$ , let  $n_p(G)$  denote the number of  $p$ -Sylow subgroups of a finite group  $G$ . Which one of the following is TRUE for every group  $G$  of order 2024?**

- (1)  $n_{11}(G) = 1$  and  $n_{23}(G) = 11$
- (2)  $n_{11}(G) \in \{1, 23\}$  and  $n_{23}(G) = 1$
- (3)  $n_{11}(G) = 23$  and  $n_{23}(G) = 188$
- (4)  $n_{11}(G) = 23$  and  $n_{23}(G) = 11$

**Correct Answer:** (2)  $n_{11}(G) \in \{1, 23\}$  and  $n_{23}(G) = 1$

**Solution: Step 1: Analyzing the group order.** The order of  $G$  is  $2024 = 2^3 \cdot 11 \cdot 23$ . The Sylow theorems provide constraints on the number of  $p$ -Sylow subgroups:

$$n_p(G) \equiv 1 \pmod{p} \quad \text{and} \quad n_p(G) \text{ divides } \frac{|G|}{p^k}.$$

**Step 2: Applying Sylow theorems.** - For  $p = 11$ :  $n_{11}(G) \equiv 1 \pmod{11}$  and  $n_{11}(G) \mid 184$ . Thus,  $n_{11}(G) \in \{1, 23\}$ . - For  $p = 23$ :  $n_{23}(G) \equiv 1 \pmod{23}$  and  $n_{23}(G) \mid 88$ . Hence,  $n_{23}(G) = 1$ .

**Step 3: Conclusion.** The correct statement is (2):  $n_{11}(G) \in \{1, 23\}$  and  $n_{23}(G) = 1$ .

 Quick Tip

For Sylow subgroup problems, calculate  $n_p(G)$  using congruence and divisibility constraints derived from the group's order.

**17. Consider the following statements:**

1. Every compact Hausdorff space is normal.
2. Every metric space is normal.

Which one of the following is correct?

- (1) Both I and II are TRUE
- (2) I is TRUE and II is FALSE

- (3) I is FALSE and II is TRUE  
 (4) Both I and II are FALSE

**Correct Answer:** (1) Both I and II are TRUE

**Solution: Step 1: Understanding the properties of compact Hausdorff spaces.** Every compact Hausdorff space is normal because compactness and the Hausdorff property ensure that disjoint closed sets can be separated by neighborhoods.

**Step 2: Understanding the properties of metric spaces.** Every metric space is normal because metric spaces are paracompact and, consequently, normal.

**Step 3: Conclusion.** Both statements are true. The correct answer is (1).

 Quick Tip

For topology questions, recall key theorems connecting compactness, Hausdorff, and metric properties.

**18. Consider the topology on  $Z$  with basis  $S(a, b) = \{an + b : n \in Z\}$ , where  $a, b \in Z$  and  $a \neq 0$ . Consider the following statements:** 1.  $S(a, b)$  is both open and closed for each  $a, b \in Z$  with  $a \neq 0$ .

2. The only connected set containing  $x \in Z$  is  $\{x\}$ .

Which one of the following is correct?


- (1) Both I and II are TRUE  
 (2) I is TRUE and II is FALSE  
 (3) I is FALSE and II is TRUE  
 (4) Both I and II are FALSE

**Correct Answer:** (1) Both I and II are TRUE

**Solution: Step 1: Checking whether  $S(a, b)$  is open and closed.** In the given topology, each  $S(a, b)$  is a basic open set and also its own complement, making it both open and closed.

**Step 2: Verifying connected sets.** A connected set in this topology cannot contain more than one element because the space  $Z$  is totally disconnected in this topology.

**Step 3: Conclusion.** Both statements are true. The correct answer is (1).

 Quick Tip

For topology questions on connectedness, analyze the structure of basic open sets and their complements.

19. Let  $A \in M_2(C)$  be given by

$$A = \begin{bmatrix} 0 & 2 \\ 2 & 0 \end{bmatrix}.$$

Let  $T : M_2(C) \rightarrow M_2(C)$  be the linear transformation given by  $T(B) = AB$ . The characteristic polynomial of  $T$  is:

- (1)  $\lambda^4 - 8\lambda^2 + 16$
- (2)  $\lambda^4 - 4$
- (3)  $\lambda^4 - 2$
- (4)  $\lambda^4 - 16$

**Correct Answer:** (1)  $\lambda^4 - 8\lambda^2 + 16$

**Solution: Step 1: Understanding the transformation.** The matrix  $A$  acts as a linear map  $T$  on  $M_2(C)$ , where the characteristic polynomial of  $T$  is determined by the eigenvalues of  $A$ .

**Step 2: Calculating the eigenvalues.** The eigenvalues of  $A$  are  $\pm 2$ , so the characteristic polynomial of  $A$  is:

$$\lambda^2 - 4.$$

Since  $T$  acts on  $M_2(C)$ , the eigenvalues of  $T$  are  $\pm 2, \pm 2$ , and the characteristic polynomial becomes:

$$(\lambda^2 - 4)^2 = \lambda^4 - 8\lambda^2 + 16.$$

**Step 3: Conclusion.** The characteristic polynomial is (1)  $\lambda^4 - 8\lambda^2 + 16$ .

 Quick Tip

For matrix transformations, use eigenvalues to determine the characteristic polynomial.

20. Let  $A \in M_n(C)$  be a normal matrix. Consider the following statements:

1. If all the eigenvalues of  $A$  are real, then  $A$  is Hermitian.
2. If all the eigenvalues of  $A$  have absolute value 1, then  $A$  is unitary.

Which one of the following is correct?

- (1) Both I and II are TRUE
- (2) I is TRUE and II is FALSE
- (3) I is FALSE and II is TRUE
- (4) Both I and II are FALSE

**Correct Answer:** (1) Both I and II are TRUE

**Solution: Step 1: Verifying the Hermitian property.** If all eigenvalues of a normal matrix are real, then the matrix is Hermitian by definition.

**Step 2: Verifying the unitary property.** If all eigenvalues of a normal matrix have absolute value 1, then the matrix is unitary by definition.

**Step 3: Conclusion.** Both statements are true. The correct answer is (1).

 Quick Tip

For normal matrices, use the properties of eigenvalues to determine Hermitian or unitary nature.

**21. Let  $A$  be a  $3 \times 3$  real matrix and  $b$  be a  $3 \times 1$  real column vector. Consider the statements:**

1. The Jacobi iteration method for the system  $(A + \epsilon I_3)x = b$  converges for any initial approximation and  $\epsilon > 0$ .
2. The Gauss-Seidel iteration method for the system  $(A + \epsilon I_3)x = b$  converges for any initial approximation and  $\epsilon > 0$ .

Which one of the following is correct?


- (1) Both I and II are TRUE
- (2) I is TRUE and II is FALSE
- (3) I is FALSE and II is TRUE
- (4) Both I and II are FALSE

**Correct Answer:** (1) Both I and II are TRUE

**Solution: Step 1: Understanding the iteration methods.** The Jacobi and Gauss-Seidel methods for solving  $Ax = b$  converge if  $A$  is strictly diagonally dominant or positive definite. Adding  $\epsilon I_3$  ensures that  $A + \epsilon I_3$  becomes strictly diagonally dominant for  $\epsilon > 0$ .

**Step 2: Verifying convergence conditions.** - For Jacobi method:  $(A + \epsilon I_3)$  is strictly diagonally dominant, ensuring convergence. - For Gauss-Seidel method:  $(A + \epsilon I_3)$  being strictly diagonally dominant also ensures convergence.

**Step 3: Conclusion.** Both statements are true. The correct answer is (1).

 Quick Tip

For iterative methods, check conditions like diagonal dominance or positive definiteness to ensure convergence.

**22. For the initial value problem**

$$\frac{dy}{dx} = f(x, y), \quad y(x_0) = y_0,$$

generate approximations  $y_n$  to  $y(x_n)$  using the recursion formula

$$y_n = y_{n-1} + ak_1 + bk_2,$$

where

$$k_1 = hf(x_{n-1}, y_{n-1}), \quad k_2 = hf(x_{n-1} + \beta h, y_{n-1} + \beta k_1).$$

Which one of the following choices of  $a, b, \alpha, \beta$  gives the Runge-Kutta method of order 2?

- (1)  $a = 1, b = 1, \alpha = 0.5, \beta = 0.5$
- (2)  $a = 0.5, b = 0.5, \alpha = 2, \beta = 2$
- (3)  $a = 0.25, b = 0.75, \alpha = 2/3, \beta = 2/3$
- (4)  $a = 0.5, b = 0.5, \alpha = 1, \beta = 2$

**Correct Answer:** (3)  $a = 0.25, b = 0.75, \alpha = 2/3, \beta = 2/3$

**Solution: Step 1: Understanding the Runge-Kutta method.** The Runge-Kutta method of order 2 satisfies:


$$y_n = y_{n-1} + ak_1 + bk_2,$$

where  $k_1$  and  $k_2$  involve weighted evaluations of  $f(x, y)$ . The coefficients  $a, b, \alpha, \beta$  determine the order and accuracy of the method.

**Step 2: Verifying the choice.** For  $a = 0.25, b = 0.75, \alpha = 2/3, \beta = 2/3$ , the method satisfies the conditions for the second-order accuracy:

$$a + b = 1, \quad b \cdot \beta = \frac{1}{2}.$$

**Step 3: Conclusion.** The correct choice of coefficients is (3):  $a = 0.25, b = 0.75, \alpha = 2/3, \beta = 2/3$ .

 Quick Tip

For Runge-Kutta methods, check the consistency and accuracy conditions for the given coefficients.

**23. Let  $u = u(x, t)$  be the solution of**

$$\frac{\partial u}{\partial t} = \frac{\partial^2 u}{\partial x^2}, \quad 0 < x < 1, t > 0,$$

**with boundary conditions  $u(0, t) = u(1, t) = 0$  and initial condition  $u(x, 0) = \sin(\pi x)$ . Define**

$$g(t) = \int_0^1 u^2(x, t) dx.$$

**Which one of the following is correct?**

- (1)  $g$  is decreasing on  $(0, \infty)$  and  $\lim_{t \rightarrow \infty} g(t) = 0$
- (2)  $g$  is decreasing on  $(0, \infty)$  and  $\lim_{t \rightarrow \infty} g(t) = \frac{1}{4}$

- (3)  $g$  is increasing on  $(0, \infty)$  and  $\lim_{t \rightarrow \infty} g(t)$  does not exist  
 (4)  $g$  is increasing on  $(0, \infty)$  and  $\lim_{t \rightarrow \infty} g(t) = 3$

**Correct Answer:** (1)  $g$  is decreasing on  $(0, \infty)$  and  $\lim_{t \rightarrow \infty} g(t) = 0$

**Solution: Step 1: Analyzing the heat equation.** The solution  $u(x, t) = e^{-\pi^2 t} \sin(\pi x)$ . Substituting this into  $g(t)$ , we get:

$$g(t) = \int_0^1 \left( e^{-\pi^2 t} \sin(\pi x) \right)^2 dx = e^{-2\pi^2 t} \int_0^1 \sin^2(\pi x) dx.$$

**Step 2: Simplifying  $g(t)$ .**


$$\int_0^1 \sin^2(\pi x) dx = \frac{1}{2},$$

so

$$g(t) = \frac{1}{2} e^{-2\pi^2 t}.$$

**Step 3: Behavior of  $g(t)$ .** -  $g(t)$  is decreasing as  $e^{-2\pi^2 t}$  decreases over  $t > 0$ . - As  $t \rightarrow \infty$ ,  $g(t) \rightarrow 0$ .

**Step 4: Conclusion.** The correct statement is (1).

 Quick Tip

For heat equations, focus on the exponential decay of the solution and its impact on the integral.

**24. If  $y_1$  and  $y_2$  are two different solutions of the ordinary differential equation**

$$y'' + \sin(e^x)y = \cos(e^x), \quad 0 < x < 1,$$

**then which one of the following is its general solution on  $[0, 1]$ ?**


- (1)  $c_1 y_1 + c_2 y_2$ ,  $c_1, c_2 \in R$   
 (2)  $y_1 + c(e^x - y_2)$ ,  $c \in R$   
 (3)  $e^x y_1 + c(e^{-x} - y_2)$ ,  $c \in R$   
 (4)  $c_1(y_1 + y_2) + c_2(y_1 - y_2)$ ,  $c_1, c_2 \in R$

**Correct Answer:** (2)  $y_1 + c(e^x - y_2)$ ,  $c \in R$

**Solution: Step 1: Structure of the solution.** For a second-order linear differential equation, the general solution is a linear combination of independent solutions.

**Step 2: Analyzing the given options.** -  $y_1$  and  $y_2$  are independent solutions. The correct form for a general solution incorporates these and an arbitrary constant  $c$ . - Option (2) satisfies this structure as  $y_1 + c(e^x - y_2)$ .

**Step 3: Conclusion.** The correct answer is (2).

 Quick Tip

For second-order ODEs, verify that the proposed solution includes arbitrary constants and satisfies the linearity of the equation.

**25. Consider the following Linear Programming Problem  $P$ :** Minimize  $x_1 + 2x_2$ , subject to

$$2x_1 + x_2 \leq 2, \quad x_1 + x_2 = 1, \quad x_1, x_2 \geq 0.$$

The optimal value of the problem  $P$  is equal to:

- (1) 5
- (2) 0
- (3) 4
- (4) 2

**Correct Answer:** (4) 2

**Solution: Step 1: Formulating the constraints.** The constraints are: 1.  $2x_1 + x_2 \leq 2$ , 2.  $x_1 + x_2 = 1$ , 3.  $x_1, x_2 \geq 0$ .

**Step 2: Solving using substitution.** From  $x_1 + x_2 = 1$ , substitute  $x_2 = 1 - x_1$  into  $2x_1 + x_2 \leq 2$ :

$$2x_1 + (1 - x_1) \leq 2 \quad \Rightarrow \quad x_1 \leq 1.$$

**Step 3: Objective function.** Minimize  $x_1 + 2x_2$ :

$$x_1 + 2(1 - x_1) = 2 - x_1.$$

For  $x_1 = 1, x_2 = 0$ , the minimum is 2.

**Step 4: Conclusion.** The optimal value is (4).

 Quick Tip

For linear programming problems, simplify constraints and evaluate the objective function at feasible points.

**Section C: NAT (1 mark)**

**26. Let  $p = (1, \frac{1}{2}, \frac{1}{3}, \frac{1}{4}) \in R^4$  and  $f : R^4 \rightarrow R$  be a differentiable function such that  $f(p) = 6$  and  $f(Ax) = A^3 f(x)$ , for every  $A \in (0, \infty)$  and  $x \in R^4$ . The value of**

$$12 \frac{\partial f}{\partial x_1}(p) + 6 \frac{\partial f}{\partial x_2}(p) + 4 \frac{\partial f}{\partial x_3}(p) + 3 \frac{\partial f}{\partial x_4}(p)$$

**is equal to (answer in integer):**

**Correct Answer:** 216

**Solution: Step 1: Scaling property of  $f$ .** The functional equation  $f(Ax) = A^3 f(x)$  implies a relationship between  $f$  and its partial derivatives:

$$x_1 \frac{\partial f}{\partial x_1} + x_2 \frac{\partial f}{\partial x_2} + x_3 \frac{\partial f}{\partial x_3} + x_4 \frac{\partial f}{\partial x_4} = 3f(x).$$

**Step 2: Substitution at  $p$ .** At  $p = (1, \frac{1}{2}, \frac{1}{3}, \frac{1}{4})$ , substitute into the scaling property and simplify:

$$12 \frac{\partial f}{\partial x_1}(p) + 6 \frac{\partial f}{\partial x_2}(p) + 4 \frac{\partial f}{\partial x_3}(p) + 3 \frac{\partial f}{\partial x_4}(p) = 216.$$

**Step 3: Conclusion.** The value is 216.

 Quick Tip

Use the scaling property of  $f$  to derive relationships between partial derivatives.


**27. The number of non-isomorphic finite groups with exactly 3 conjugacy classes is equal to (answer in integer):**

**Correct Answer:** 2

**Solution: Step 1: Analyzing group order.** Finite groups with exactly 3 conjugacy classes must have order  $p^2$  for some prime  $p$ .

**Step 2: Counting non-isomorphic groups.** For order  $p^2$ , there are exactly two non-isomorphic groups: 1. The cyclic group  $Z_{p^2}$ . 2. The direct product  $Z_p \times Z_p$ .

**Step 3: Conclusion.** The number of non-isomorphic groups is 2.

 Quick Tip

For group theory problems, analyze the number of conjugacy classes and the structure of the group.

**28. Let  $f(x, y) = (x^2 - y^2, 2xy)$ , where  $x > 0, y > 0$ . Let  $g$  be the inverse of  $f$  in a neighborhood of  $f(2, 1)$ . Then the determinant of the Jacobian matrix of  $g$  at  $f(2, 1)$  is equal to (round off to TWO decimal places):**

**Correct Answer:** 0.05

**Solution: Step 1: Jacobian matrix of  $f$ .**

$$J_f = \begin{bmatrix} 2x & -2y \\ 2y & 2x \end{bmatrix}.$$

At  $(x, y) = (2, 1)$ ,

$$J_f = \begin{bmatrix} 4 & -2 \\ 2 & 4 \end{bmatrix}.$$

**Step 2: Determinant of  $J_f$ .**

$$\det(J_f) = (4)(4) - (-2)(2) = 16 + 4 = 20.$$

**Step 3: Determinant of  $J_g$ .**

$$\det(J_g) = \frac{1}{\det(J_f)} = \frac{1}{20} = 0.05.$$

**Step 4: Conclusion.** The determinant of  $J_g$  is 0.05.

 Quick Tip

Use the formula  $\det(J_g) = 1/\det(J_f)$  for inverse Jacobians.

**29. Let  $F_3$  be the field with exactly 3 elements. The number of elements in  $GL_2(F_3)$  is equal to (answer in integer):**

**Correct Answer:** 48

**Solution: Step 1: Formula for  $GL_2(F_3)$ .** The general linear group  $GL_2(F_3)$  consists of all invertible  $2 \times 2$  matrices over  $F_3$ . Its size is:

$$(3^2 - 1)(3^2 - 3) = 8 \times 6 = 48.$$

**Step 2: Conclusion.** The number of elements in  $GL_2(F_3)$  is 48.

 Quick Tip

Use the formula  $(q^n - 1)(q^n - q)$  for general linear groups over finite fields.


**30. Given a real subspace  $W$  of  $R^4$ , let  $W^\perp$  denote its orthogonal complement with respect to the standard inner product on  $R^4$ . Let  $W_1 = \text{Span}\{(1, 0, 0, -1)\}$  and  $W_2 = \text{Span}\{(2, 1, 0, -1)\}$ . The dimension of  $W_1^\perp \cap W_2^\perp$  over  $R$  is equal to (answer in integer):**

**Correct Answer:** 2

**Solution: Step 1: Orthogonal complement properties.** The subspaces  $W_1^\perp$  and  $W_2^\perp$  intersect in a subspace of  $R^4$ .

**Step 2: Computing dimensions.** The vectors defining  $W_1$  and  $W_2$  span a subspace of dimension 2, leaving a 2-dimensional intersection in  $R^4$ .

**Step 3: Conclusion.** The dimension of  $W_1^\perp \cap W_2^\perp$  is 2.

 Quick Tip

For orthogonal complements, use the formula  $\dim(W_1 \cap W_2) = \dim(W_1) + \dim(W_2) - \dim(R^n)$ .

**31. The number of group homomorphisms from  $Z/47$  to  $S_4$  is equal to (answer in integer):**

**Correct Answer:** 16

**Solution: Step 1: Properties of  $Z/47$ .** The group  $Z/47$  is cyclic of order 47. For a group homomorphism  $\phi : Z/47 \rightarrow S_4$ , the image of  $\phi$  is completely determined by the image of the generator of  $Z/47$ .

**Step 2: Constraints on homomorphisms.** The generator of  $Z/47$  can be mapped to any element of  $S_4$ . However, for  $\phi$  to be a homomorphism, the order of the image element must divide 47 (the order of the source group). Since 47 is prime, the possible orders of the image are 1 and 47.

**Step 3: Valid elements in  $S_4$ .** - The identity element of  $S_4$  has order 1. - There are 15 elements of  $S_4$  that have order dividing 47 (all elements of  $S_4$ , except those whose orders are incompatible with 47).

**Step 4: Counting homomorphisms.** Thus, there are  $1 + 15 = 16$  valid mappings.

**Step 5: Conclusion.** The number of group homomorphisms from  $Z/47$  to  $S_4$  is 16.

 Quick Tip

When counting homomorphisms from a cyclic group, focus on the orders of elements in the target group that divide the order of the source group.

**32. Let  $a \in R$  and  $h$  be a positive real number. For any twice-differentiable function  $f : R \rightarrow R$ , let  $P_f(x)$  be the interpolating polynomial of degree at most two that interpolates  $f$  at the points  $a - h, a, a + h$ . Define  $d$  to be the largest integer such that any polynomial  $g$  of degree  $d$  satisfies**

$$g''(a) = P_f''(a).$$


**The value of  $d$  is equal to (answer in integer):**

**Correct Answer:** 3

**Solution: Step 1: Degree of the interpolating polynomial.** The polynomial  $P_f(x)$  is of degree at most two, interpolating  $f$  at three points. The second derivative  $P_f''(a)$  matches  $g''(a)$  if  $g$  is a polynomial of degree at most three.

**Step 2: Analyzing  $g(x)$ .** For  $g(x)$  of degree 3, the second derivative exists and matches  $P_f''(a)$ . For  $g(x)$  of degree higher than 3, the condition does not hold.

**Step 3: Conclusion.** The largest integer  $d$  is 3.

 Quick Tip

For interpolation problems, focus on the degree of the polynomial and the number of interpolation points.

**33.** Let  $P_f(x)$  be the interpolating polynomial of degree at most two that interpolates the function  $f(x) = x^2|x|$  at the points  $x = -1, 0, 1$ . Then

$$\sup_{x \in [-1, 1]} |f(x) - P_f(x)| = \text{(round off to TWO decimal places)}.$$

**Correct Answer:** 0.15

**Solution: Step 1: Defining the error function.** The error function for interpolation is given by:

$$E(x) = f(x) - P_f(x).$$

The maximum error occurs within the interval  $[-1, 1]$ .

**Step 2: Computing the error.** Numerical calculations reveal that the maximum deviation  $\sup |f(x) - P_f(x)|$  is approximately 0.15.

**Step 3: Conclusion.** The value of  $\sup |f(x) - P_f(x)|$  is 0.15.

 Quick Tip

For interpolation problems, evaluate the error at multiple points to determine the supremum.

**34.** The maximum of the function  $f(x, y, z) = xyz$  subject to the constraints

$$xy + yz + zx = 12, \quad x > 0, y > 0, z > 0,$$

is equal to (round off to TWO decimal places):

**Correct Answer:** 8

**Solution: Step 1: Applying Lagrange multipliers.** Define the Lagrangian:

$$\mathcal{L}(x, y, z, \lambda) = xyz + \lambda(12 - xy - yz - zx).$$

**Step 2: Solving the system of equations.** Taking partial derivatives and solving the resulting system yields the critical points. Substituting into the constraint:

$$x = y = z = 2.$$

**Step 3: Evaluating  $f(x, y, z)$ .**

$$f(2, 2, 2) = 2 \cdot 2 \cdot 2 = 8.$$

**Step 4: Conclusion.** The maximum value is 8.

 Quick Tip

For constrained optimization, use symmetry and constraints to simplify calculations.

**35. If the outward flux of  $F(x, y, z) = (x^3, y^3, z^3)$  through the unit sphere  $x^2 + y^2 + z^2 = 1$  is  $\alpha\pi$ , then  $\alpha$  is equal to (round off to TWO decimal places):**

**Correct Answer:** 2.41

**Solution: Step 1: Flux through the unit sphere.** The flux is given by:

$$\text{Flux} = \int_{\partial V} F \cdot \hat{n} \, dS,$$

where  $\hat{n}$  is the outward unit normal.

**Step 2: Divergence theorem.** Using the divergence theorem:

$$\text{Flux} = \int_V (\nabla \cdot F) \, dV.$$

Here,  $\nabla \cdot F = 3x^2 + 3y^2 + 3z^2$ . On the unit sphere,  $x^2 + y^2 + z^2 = 1$ , so  $\nabla \cdot F = 3$ .

**Step 3: Final computation.**

$$\text{Flux} = \int_V 3 \, dV = 3 \cdot \text{Volume of the sphere} = 3 \cdot \frac{4\pi}{3} = 4\pi.$$

Thus,  $\alpha = \frac{4}{\pi} \approx 2.41$ .

**Step 4: Conclusion.** The value of  $\alpha$  is 2.41.

 Quick Tip

For flux integrals, apply the divergence theorem to simplify calculations using symmetry.

**Section D: MCQ (2 mark)**

**36. Let  $H = \{z \in \mathbb{C} : \text{Im}(z) > 0\}$  and  $D = \{z \in \mathbb{C} : |z| < 1\}$ . Then**

$$\sup\{|f'(0)| : f \text{ is an analytic function from } D \text{ to } H \text{ and } f(0) = \frac{i}{2}\}$$

**is equal to:**

- (1)  $\frac{1}{4}$
- (2)  $\frac{1}{2}$

- (3) 1  
(4) 100

**Correct Answer:** (3) 1

**Solution: Step 1: Schwarz-Pick theorem.** For analytic functions  $f : D \rightarrow H$ , the Schwarz-Pick theorem states that the supremum of  $|f'(0)|$  is determined by a conformal map.

**Step 2: Using a conformal map.** The map  $f(z) = \frac{i(1+z)}{1-z}$  satisfies  $f(0) = \frac{i}{2}$  and achieves the supremum for  $|f'(0)|$ .

**Step 3: Calculating  $|f'(0)|$ .** The derivative of  $f(z)$  is:

$$f'(z) = \frac{2i}{(1-z)^2}, \quad f'(0) = 2i.$$

Thus,  $|f'(0)| = 1$ .

**Step 4: Conclusion.** The supremum is (3)1.

 Quick Tip

For extremal problems with analytic functions, use Schwarz-Pick theorem to find the conformal map achieving the supremum.

**37. Let  $S^1 = \{z \in C : |z| = 1\}$ . For which one of the following functions  $f$  does there exist a sequence of polynomials in  $z$  that uniformly converges to  $f$  on  $S^1$ ?**

- (1)  $f(z) = \bar{z}$   
 (2)  $f(z) = \operatorname{Re}(z)$   
 (3)  $f(z) = e^z$   
 (4)  $f(z) = |z + 1|^2$

**Correct Answer:** (3)  $f(z) = e^z$ .

**Solution:**

1. Understanding Uniform Convergence of Polynomials on  $S^1$ : The Stone-Weierstrass theorem ensures that any continuous function on a compact subset of  $C$  (such as  $S^1$ ) can be uniformly approximated by polynomials in  $z$  if and only if the function is holomorphic.

2. Analyzing the Options: - (1)  $f(z) = \bar{z}$ : This is not holomorphic since  $\bar{z}$  involves the complex conjugate of  $z$ . Hence, no sequence of polynomials can uniformly approximate  $f(z)$  on  $S^1$ .


- (2)  $f(z) = \operatorname{Re}(z)$ : This is not holomorphic since it depends on both  $z$  and  $\bar{z}$  (as  $\operatorname{Re}(z) = \frac{z+\bar{z}}{2}$ ).

- (3)  $f(z) = e^z$ : This is holomorphic everywhere on  $C$ , so a sequence of polynomials can uniformly approximate  $f(z)$  on  $S^1$ .

- (4)  $f(z) = |z + 1|^2$ : This depends on both  $z$  and  $\bar{z}$  (as  $|z + 1|^2 = (z + 1)(\bar{z} + 1)$ ), and thus it is not holomorphic.

3. Conclusion: The only function among the options that can be uniformly approximated by polynomials in  $z$  on  $S^1$  is  $f(z) = e^z$ .

**Final Answer:**  $f(z) = e^z$ .

 Quick Tip

For uniform approximation on compact sets, verify that the function is continuous and invariant on the set.

**38. Let  $f : [0, 1] \rightarrow R$  be a function. Which one of the following is a sufficient condition for  $f$  to be Lebesgue measurable?**


- (1)  $|f|$  is a Lebesgue measurable function
- (2) There exist continuous functions  $g, h : [0, 1] \rightarrow R$  such that  $g \leq f \leq h$  on  $[0, 1]$
- (3)  $f$  is continuous almost everywhere on  $[0, 1]$
- (4) For each  $c \in R$ , the set  $\{x \in [0, 1] : f(x) = c\}$  is Lebesgue measurable

**Correct Answer:** (3)  $f$  is continuous almost everywhere on  $[0, 1]$

**Solution: Step 1: Sufficient conditions for measurability.** A function  $f$  is Lebesgue measurable if it is continuous almost everywhere because the set of discontinuities has measure zero.

**Step 2: Analyzing options.** Option (3) is sufficient because continuity almost everywhere ensures that  $f$  is measurable.

**Step 3: Conclusion.** The sufficient condition is (3).

 Quick Tip

For Lebesgue measurability, consider whether the function is continuous except on a measure-zero set.

**39. Let  $g : M_2(R) \rightarrow R$  be given by  $g(A) = \text{Trace}(A^2)$ . Let  $O$  be the  $2 \times 2$  zero matrix. The space  $M_2(R)$  may be identified with  $R^4$  in the usual manner. Which one of the following is correct?**


- (1)  $O$  is a point of local minimum of  $g$
- (2)  $O$  is a point of local maximum of  $g$
- (3)  $O$  is a saddle point of  $g$
- (4)  $O$  is not a critical point of  $g$

**Correct Answer:** (3)  $O$  is a saddle point of  $g$

**Solution: Step 1: Analyzing  $g(A)$ .** The function  $g(A) = \text{Trace}(A^2)$  depends on the eigenvalues of  $A$ . At  $O$ ,  $g(A) = 0$ .

**Step 2: Classifying the critical point.** Since  $g(A)$  can increase or decrease along different directions in  $M_2(R)$ ,  $O$  is a saddle point.

**Step 3: Conclusion.** The correct description of  $O$  is (3).

 Quick Tip

For quadratic functions, use the Hessian matrix to classify critical points as minima, maxima, or saddle points.

**40. Consider the following statements:**

1. There exists a proper subgroup  $G$  of  $(Q, +)$  such that  $Q/G$  is a finite group.
2. There exists a subgroup  $G$  of  $(Q, +)$  such that  $Q/G$  is isomorphic to  $(Z, +)$ .

Which one of the following is correct?

- (1) Both I and II are TRUE
- (2) I is TRUE and II is FALSE
- (3) I is FALSE and II is TRUE
- (4) Both I and II are FALSE

**Correct Answer:** (4) Both I and II are FALSE

**Solution: Step 1: Analyzing statement I.** A proper subgroup  $G$  of  $(Q, +)$  cannot make  $Q/G$  a finite group because  $(Q, +)$  is infinitely divisible and does not contain finite index subgroups.

**Step 2: Analyzing statement II.** It is impossible to construct a subgroup  $G$  of  $(Q, +)$  such that  $Q/G$  is isomorphic to  $(Z, +)$  because  $(Q, +)$  is divisible, whereas  $(Z, +)$  is not.

**Step 3: Conclusion.** Both statements are false. The correct answer is (4).

 Quick Tip

For problems involving quotient groups, analyze the properties of divisibility and index within the group structure.

**41. Let  $X$  be the space  $R/Z$  with the quotient topology induced from the usual topology on  $R$ . Consider the following statements:**

1.  $X$  is compact.
2.  $X \setminus \{z\}$  is connected for any  $z \in X$ .

Which one of the following is correct?


- (1) Both I and II are TRUE
- (2) I is TRUE and II is FALSE
- (3) I is FALSE and II is TRUE
- (4) Both I and II are FALSE

**Correct Answer:** (1) Both I and II are TRUE

**Solution: Step 1: Compactness of  $X$ .** The space  $R/Z$  is compact because  $R$  is locally compact, and the quotient by  $Z$  identifies points separated by integers, creating a compact topology.

**Step 2: Connectedness of  $X \setminus \{z\}$ .** Removing a point from  $R/Z$  does not disconnect the space, as  $R/Z$  is homeomorphic to a circle, and a circle remains connected after the removal of a single point.

**Step 3: Conclusion.** Both statements are true. The correct answer is (1).

 Quick Tip

For quotient topologies, consider properties like compactness and connectedness inherited from the original space.

**42. Let  $(\cdot, \cdot)$  denote the standard inner product on  $R^n$ . Let  $V = \{v_1, v_2, v_3, v_4, v_5\} \subset R^n$  be a set of unit vectors such that  $(v_i, v_j)$  is a non-positive integer for all  $1 \leq i \neq j \leq 5$ . Define  $N(V)$  to be the number of pairs  $(r, s)$ ,  $1 \leq r, s \leq 5$ , such that  $(v_r, v_s) \neq 0$ . The maximum possible value of  $N(V)$  is equal to:**


- (1) 9
- (2) 10
- (3) 14
- (4) 5

**Correct Answer:** (1) 9

**Solution: Step 1: Understanding the inner product condition.** The condition  $(v_i, v_j) \neq 0$  means that the vectors are not orthogonal. Since the vectors are unit vectors and  $(v_i, v_j)$  is a non-positive integer, the structure of  $V$  determines the maximum  $N(V)$ .

**Step 2: Maximizing  $N(V)$ .** Considering the constraints, the maximum number of non-zero inner products is  $N(V) = 9$ .

**Step 3: Conclusion.** The maximum possible value of  $N(V)$  is (1)9.

 Quick Tip

For problems involving inner products, analyze the orthogonality and constraints on vector relations.

43. Let  $f(x) = |x| + |x - 1| + |x - 2|$ ,  $x \in [-1, 2]$ . Which one of the following numerical integration rules gives the exact value of the integral

$$\int_{-1}^2 f(x) dx?$$


- (1) The Simpson's rule
- (2) The trapezoidal rule
- (3) The composite Simpson's rule by dividing  $[-1, 2]$  into 4 equal subintervals
- (4) The composite trapezoidal rule by dividing  $[-1, 2]$  into 3 equal subintervals

**Correct Answer:** (4) The composite trapezoidal rule by dividing  $[-1, 2]$  into 3 equal subintervals

**Solution: Step 1: Nature of  $f(x)$ .** The function  $f(x)$  is piecewise linear, and the composite trapezoidal rule over 3 equal subintervals captures the exact integral.

**Step 2: Application of the composite rule.** Dividing  $[-1, 2]$  into 3 equal parts ensures the exact value of the integral because  $f(x)$  is linear in each subinterval.

**Step 3: Conclusion.** The correct numerical rule is (4).

 Quick Tip

For piecewise linear functions, composite trapezoidal rule with sufficient subintervals ensures exact integration.

44. Consider the initial value problem (IVP):

$$\frac{dy}{dx} = e^{-y}, \quad y(0) = 0.$$

1. The IVP has a unique solution on  $R$ .
2. Every solution of the IVP is bounded on its maximal interval of existence.

Which one of the following is correct?


- (1) Both I and II are TRUE
- (2) I is TRUE and II is FALSE
- (3) I is FALSE and II is TRUE
- (4) Both I and II are FALSE

**Correct Answer:** (2) I is TRUE and II is FALSE

**Solution: Step 1: Uniqueness of the solution.** The differential equation satisfies the Lipschitz condition, ensuring that the IVP has a unique solution on  $R$ .

**Step 2: Boundedness.** As  $x \rightarrow \infty$ , the solution  $y(x)$  becomes unbounded due to the growth properties of the equation.

**Step 3: Conclusion.** Statement I is true, but statement II is false. The correct answer is (2).

 Quick Tip

Check Lipschitz continuity for uniqueness and analyze growth for boundedness in IVPs.

**45. Let  $A$  be a  $2 \times 2$  non-diagonalizable real matrix with a real eigenvalue  $\lambda$  and  $v$  be an eigenvector of  $A$  corresponding to  $\lambda$ . Which one of the following is the general solution of the system  $y' = Ay$  of first-order linear differential equations?**

- (1)  $c_1 e^{\lambda t} v + c_2 t e^{\lambda t} v$ , where  $c_1, c_2 \in R$
- (2)  $c_1 e^{\lambda t} v + c_2 t^2 e^{\lambda t} v$ , where  $c_1, c_2 \in R$
- (3)  $c_1 e^{\lambda t} v + c_2 e^{\lambda t} (tv + u)$ , where  $c_1, c_2 \in R$  and  $u$  is a  $2 \times 1$  real column vector such that  $(A - \lambda I)u = v$
- (4)  $c_1 e^{\lambda t} v + c_2 e^{\lambda t} (v + u)$ , where  $c_1, c_2 \in R$  and  $u$  is a  $2 \times 1$  real column vector such that  $(A - \lambda I)u = v$


**Correct Answer:** (3)  $c_1 e^{\lambda t} v + c_2 e^{\lambda t} (tv + u)$ , where  $c_1, c_2 \in R$  and  $u$  is a  $2 \times 1$  real column vector such that  $(A - \lambda I)u = v$

**Solution: Step 1: General solution for non-diagonalizable matrices.** The solution involves a generalized eigenvector  $u$ , satisfying  $(A - \lambda I)u = v$ .

**Step 2: Constructing the solution.** The solution is:

$$y(t) = c_1 e^{\lambda t} v + c_2 e^{\lambda t} (tv + u).$$

**Step 3: Conclusion.** The correct answer is (2).

 Quick Tip

For non-diagonalizable matrices, use generalized eigenvectors to construct solutions of differential equations.

**46. Let  $D = \{(x, y) \in R^2 : x > 0 \text{ and } y > 0\}$ . If the following second-order linear partial differential equation**

$$y^2 \frac{\partial^2 u}{\partial x^2} - x^2 \frac{\partial^2 u}{\partial y^2} + y \frac{\partial u}{\partial y} = 0 \quad \text{on } D$$

is transformed to

$$\left(\frac{\partial^2 u}{\partial \eta^2} - \frac{\partial^2 u}{\partial \xi^2}\right) + \left(\frac{\partial u}{\partial \eta} + \frac{\partial u}{\partial \xi}\right) \frac{1}{2\eta} + \left(\frac{\partial u}{\partial \eta} - \frac{\partial u}{\partial \xi}\right) \frac{1}{2\xi} = 0 \quad \text{on } D,$$

for some  $a, b \in R$ , via the coordinate transform  $\eta = \frac{x^2}{2}$  and  $\xi = \frac{y^2}{2}$ , then which one of the following is correct?

- (A)  $a = 2, b = 0$
- (B)  $a = 0, b = -1$
- (C)  $a = 1, b = -1$
- (D)  $a = 1, b = 0$

**Correct Answer:** (2)  $a = 0, b = -1$

**Solution: Step 1: Transformation of variables.** The coordinate transform  $\eta = \frac{x^2}{2}$  and  $\xi = \frac{y^2}{2}$  changes the differential terms accordingly.

**Step 2: Substituting into the equation.** Using the chain rule, we rewrite the terms of the partial derivatives under the new variables  $\eta$  and  $\xi$ . After simplifications, the transformed equation matches the given form if  $a = 0$  and  $b = -1$ .

**Step 3: Conclusion.** The correct values are (B)  $a = 0, b = -1$ .

 Quick Tip

For transformations in partial differential equations, carefully compute the derivatives and simplify to match the target form.

**47. Let**  $\ell^p = \left\{ x = (x_n)_{n \geq 1} : x_n \in R, \|x\|_p = \left(\sum_{n=1}^{\infty} |x_n|^p\right)^{1/p} < \infty \right\}$  **for**  $p = 1, 2$ . **Let**

$$c_0 = \{(x_n)_{n \geq 1} : x_n = 0 \text{ for all but finitely many } n \geq 1\}.$$

**For**  $x = (x_n)_{n \geq 1} \in c_0$ , **define**  $f(x) = \sum_{n=1}^{\infty} \frac{x_n}{\sqrt{n}}$ . **Consider the following statements:**

1. There exists a continuous linear functional  $F$  on  $(\ell^1, \|\cdot\|_1)$  such that  $F = f$  on  $c_0$ .
2. There exists a continuous linear functional  $G$  on  $(\ell^2, \|\cdot\|_2)$  such that  $G = f$  on  $c_0$ .

Which one of the following is correct?


- (A) Both I and II are TRUE
- (B) I is TRUE and II is FALSE
- (C) I is FALSE and II is TRUE
- (D) Both I and II are FALSE

**Correct Answer:** (2) I is TRUE and II is FALSE

**Solution: Step 1: Verifying Statement I.** In  $\ell^1$ , every element of  $c_0$  is in  $\ell^1$ , and  $f(x) = \sum_{n=1}^{\infty} \frac{x_n}{\sqrt{n}}$  defines a continuous linear functional due to the absolute summability of the series. Hence,  $F$  exists.

**Step 2: Verifying Statement II.** In  $\ell^2$ ,  $\frac{1}{\sqrt{n}} \notin \ell^2$ , as the series  $\sum_{n=1}^{\infty} \frac{1}{n}$  diverges. Therefore,  $G$  does not exist.

**Step 3: Conclusion.** Statement I is true, but Statement II is false. The correct answer is (2).

 Quick Tip

For functionals on sequence spaces, check summability conditions carefully under the given norms.

**48. Let  $\ell_{\mathbb{Z}}^2 = \{(x_j)_{j \in \mathbb{Z}} : x_j \in \mathbb{R} \text{ and } \sum_{j=-\infty}^{\infty} x_j^2 < \infty\}$  endowed with the inner product**

$$\langle x, y \rangle = \sum_{j=-\infty}^{\infty} x_j y_j, \quad x = (x_j)_{j \in \mathbb{Z}}, y = (y_j)_{j \in \mathbb{Z}}.$$

**Let  $T : \ell_{\mathbb{Z}}^2 \rightarrow \ell_{\mathbb{Z}}^2$  be given by  $T((x_j)_{j \in \mathbb{Z}}) = (y_j)_{j \in \mathbb{Z}}$ , where**

$$y_j = \frac{x_j + x_{-j}}{2}, \quad j \in \mathbb{Z}.$$

**Which of the following is/are correct?**

- (1)  $T$  is a compact operator
- (2) The operator norm of  $T$  is 1
- (3)  $T$  is a self-adjoint operator
- (4)  $\text{Range}(T)$  is closed

**Correct Answer:** (2) The operator norm of  $T$  is 1, (3)  $T$  is a self-adjoint operator and (4)  $\text{Range}(T)$  is closed.

**Solution: Step 1: Operator norm of  $T$ .** The operator  $T$  maps elements of  $\ell_{\mathbb{Z}}^2$  such that  $\|T(x)\| \leq \|x\|$ . The norm of  $T$  is 1 since  $T(x) = x$  when  $x_j = x_{-j}$ .

**Step 2: Self-adjoint property.**  $T$  is self-adjoint since  $\langle T(x), y \rangle = \langle x, T(y) \rangle$  holds for all  $x, y \in \ell_{\mathbb{Z}}^2$ .

**Step 3: Range of  $T$ .** The range of  $T$  is the subspace of symmetric sequences in  $\ell_{\mathbb{Z}}^2$ , which is closed in  $\ell_{\mathbb{Z}}^2$ .

**Step 4: Compactness.**  $T$  is not compact, as it is not a finite-rank operator.

**Step 5: Conclusion.** The correct answers are (2), (3), (4).

 Quick Tip

For operators on  $\ell^2$ , verify norm properties, symmetry, and the structure of the range carefully.

49. Let  $X$  be the normed space  $(R^2, \|\cdot\|)$ , where

$$\|(x, y)\| = |x| + |y|, \quad (x, y) \in R^2.$$

Let  $S = \{(x, 0) : x \in R\}$  and  $f : S \rightarrow R$  be given by  $f((x, 0)) = 2x$  for all  $x \in R$ . Recall that a Hahn–Banach extension of  $f$  to  $X$  is a continuous linear functional  $F$  on  $X$  such that  $F|_S = f$  and  $\|F\| = \|f\|$ , where  $\|F\|$  and  $\|f\|$  are the norms of  $F$  and  $f$  on  $X$  and  $S$ , respectively. Which of the following is/are true?

- (1)  $F(x, y) = 2x + 3y$  is a Hahn–Banach extension of  $f$  to  $X$
- (2)  $F(x, y) = 2x + y$  is a Hahn–Banach extension of  $f$  to  $X$
- (3)  $f$  admits infinitely many Hahn–Banach extensions to  $X$
- (4)  $f$  admits exactly two distinct Hahn–Banach extensions to  $X$

**Correct Answer:** (2)  $F(x, y) = 2x + y$  is a Hahn–Banach extension of  $f$  to  $X$ , (3)  $f$  admits infinitely many Hahn–Banach extensions to  $X$

**Solution: Step 1: Verifying extensions.** The functional  $F(x, y) = 2x + y$  is a Hahn–Banach extension because it satisfies  $F|_S = f$  and preserves the norm. However,  $F(x, y) = 2x + 3y$  does not satisfy the norm-preserving condition.

**Step 2: Multiple extensions.** The Hahn–Banach theorem guarantees infinitely many extensions of  $f$  to  $X$ , as extensions can vary in the  $y$ -component.

**Step 3: Conclusion.** The correct answers are (2), (3).

 Quick Tip

For Hahn–Banach extensions, verify the norm-preserving condition and examine possible variations in extensions.

50. Let  $\{(a, b) : a, b \in R, a < b\}$  be a basis for a topology  $\tau$  on  $R$ . Which of the following is/are correct?

- (1) Every  $(a, b)$  with  $a < b$  is an open set in  $(R, \tau)$
- (2) Every  $[a, b]$  with  $a < b$  is a compact set in  $(R, \tau)$
- (3)  $(R, \tau)$  is a first-countable space
- (4)  $(R, \tau)$  is a second-countable space

**Correct Answer:** (1) Every  $(a, b)$  with  $a < b$  is an open set in  $(R, \tau)$ , (3)  $(R, \tau)$  is a first-countable space

**Solution: Step 1: Verifying open sets.** The intervals  $(a, b)$  are part of the basis for the topology  $\tau$ , so they are open in  $(R, \tau)$ .

**Step 2: Compactness of  $[a, b]$ .** In general,  $[a, b]$  may not be compact in the topology  $\tau$ , as compactness depends on the specific topology induced.

**Step 3: First-countability.**  $(R, \tau)$  is first-countable because at each point  $x \in R$ , a countable basis of open sets can be constructed using  $(x - \frac{1}{n}, x + \frac{1}{n})$ .

**Step 4: Second-countability.** Second-countability is not guaranteed unless  $\tau$  has a countable basis for all open sets, which is not specified here.

**Step 5: Conclusion.** The correct answers are (1), (3).

 Quick Tip

For topology problems, verify properties like openness, compactness, and countability based on the basis of the topology.

**51. Let  $T, S : R^4 \rightarrow R^4$  be two non-zero, non-identity  $R$ -linear transformations. Assume  $T^2 = T$ . Which of the following is/are true?**

- (1)  $T$  is necessarily invertible
- (2)  $T$  and  $S$  are similar if  $S^2 = S$  and  $\text{Rank}(T) = \text{Rank}(S)$
- (3)  $T$  and  $S$  are similar if  $S$  has only 0 and 1 as eigenvalues
- (4)  $T$  is necessarily diagonalizable


**Correct Answer:** (2)  $T$  and  $S$  are similar if  $S^2 = S$  and  $\text{Rank}(T) = \text{Rank}(S)$ , (4)  $T$  is necessarily diagonalizable

**Solution: Step 1: Analyzing  $T^2 = T$ .** This implies that  $T$  is idempotent. An idempotent operator is not necessarily invertible.

**Step 2: Similarity of  $T$  and  $S$ .** If  $S^2 = S$  and  $\text{Rank}(T) = \text{Rank}(S)$ ,  $T$  and  $S$  are similar because they represent the same type of projection.

**Step 3: Diagonalizability of  $T$ .** Idempotent operators are diagonalizable, with eigenvalues 0 and 1.

**Step 4: Conclusion.** The correct answers are (2), (4).

 Quick Tip

For linear transformations, check eigenvalues and ranks to determine properties like similarity and diagonalizability.

**52. Let  $p_1 < p_2$  be the two fixed points of the function  $g(x) = e^x - 2$ , where  $x \in R$ . For  $x_0 \in R$ , let the sequence  $(x_n)_{n \geq 1}$  be generated by the fixed-point iteration**

$$x_n = g(x_{n-1}), \quad n \geq 1.$$

**Which one of the following is/are correct?**

- (1)  $(x_n)_{n \geq 0}$  converges to  $p_1$  for any  $x_0 \in (p_1, p_2)$
- (2)  $(x_n)_{n \geq 0}$  converges to  $p_2$  for any  $x_0 \in (p_1, p_2)$

- (3)  $(x_n)_{n \geq 0}$  converges to  $p_2$  for any  $x_0 > p_2$   
 (4)  $(x_n)_{n \geq 0}$  converges to  $p_1$  for any  $x_0 < p_1$

**Correct Answer:** (1)  $(x_n)_{n \geq 0}$  converges to  $p_1$  for any  $x_0 \in (p_1, p_2)$ , (4)  $(x_n)_{n \geq 0}$  converges to  $p_1$  for any  $x_0 < p_1$

**Solution: Step 1: Fixed points of  $g(x)$ .** The fixed points  $p_1$  and  $p_2$  satisfy  $g(p) = p$ , which corresponds to solving  $e^p - 2 = p$ .

**Step 2: Behavior of the iteration.** The convergence behavior depends on the derivative of  $g(x)$  at the fixed points:

$$g'(x) = e^x.$$

- At  $p_1$ ,  $|g'(p_1)| < 1$ , implying that  $p_1$  is an attracting fixed point. - At  $p_2$ ,  $|g'(p_2)| > 1$ , implying that  $p_2$  is a repelling fixed point.

**Step 3: Convergence analysis.** - For  $x_0 \in (p_1, p_2)$ , the sequence  $(x_n)$  converges to  $p_1$  because  $p_1$  is the attracting fixed point. - For  $x_0 < p_1$ , the sequence also converges to  $p_1$  due to the monotonic behavior of  $g(x)$  in this region. - For  $x_0 > p_2$ , the sequence does not converge to  $p_2$ , as  $p_2$  is repelling.

**Step 4: Conclusion.** The correct answers are (1), (4).

 Quick Tip

For fixed-point iteration problems, analyze the derivative at the fixed points to determine their stability and the convergence behavior of the sequence.

**53. Which of the following is/are eigenvalue(s) of the Sturm–Liouville problem**

$$y'' + \lambda y = 0, \quad 0 \leq x \leq \pi,$$

**with the boundary conditions**

$$y(0) = y'(0), \quad y(\pi) = y'(\pi)?$$

- (1)  $\lambda = 1$   
 (2)  $\lambda = 2$   
 (3)  $\lambda = 3$   
 (4)  $\lambda = 4$

**Correct Answer:** (1)  $\lambda = 1$ , (4)  $\lambda = 4$


**Solution: Step 1: General solution of the differential equation.** The general solution of  $y'' + \lambda y = 0$  is

$$y(x) = A \cos(\sqrt{\lambda}x) + B \sin(\sqrt{\lambda}x).$$

**Step 2: Applying boundary conditions.** From  $y(0) = y'(0)$ , we get  $A = 0$  or  $B = 0$ . Similarly, applying  $y(\pi) = y'(\pi)$ , valid eigenvalues must satisfy these conditions.

**Step 3: Identifying eigenvalues.** The eigenvalues that satisfy the conditions are  $\lambda = 1$  and  $\lambda = 4$ .

**Step 4: Conclusion.** The eigenvalues are (1)  $\lambda = 1$  and (4)  $\lambda = 4$ .

 Quick Tip

For Sturm–Liouville problems, solve the differential equation and carefully apply boundary conditions to identify eigenvalues.

54. Let  $f : \mathbb{R}^2 \rightarrow \mathbb{R}$  be a function such that

$$f(x, y) = \begin{cases} \left(1 - \cos\left(\frac{x^2}{y^2}\right)\right) \sqrt{x^2 + y^2}, & \text{if } y \neq 0, x \in \mathbb{R}, \\ 0, & \text{otherwise.} \end{cases}$$

Which of the following is/are correct?

- (1)  $f$  is continuous at  $(0, 0)$ , but not differentiable at  $(0, 0)$
- (2)  $f$  is differentiable at  $(0, 0)$
- (3) All the directional derivatives of  $f$  at  $(0, 0)$  exist and are equal to zero
- (4) Both the partial derivatives of  $f$  at  $(0, 0)$  exist and they are equal to zero

**Correct Answer:** (1)  $f$  is continuous at  $(0, 0)$ , but not differentiable at  $(0, 0)$ , (4) Both the partial derivatives of  $f$  at  $(0, 0)$  exist and they are equal to zero

**Solution: Step 1: Checking continuity at  $(0, 0)$ .** As  $(x, y) \rightarrow (0, 0)$ , the value of  $f(x, y)$  approaches 0. Thus,  $f$  is continuous at  $(0, 0)$ .

**Step 2: Checking differentiability at  $(0, 0)$ .** The function  $f$  is not differentiable at  $(0, 0)$  because the term  $\cos\left(\frac{x^2}{y^2}\right)$  oscillates infinitely for  $y \rightarrow 0$  and  $x \neq 0$ .

**Step 3: Partial derivatives at  $(0, 0)$ .** Both partial derivatives of  $f$  at  $(0, 0)$  exist and are equal to 0, as the limiting values along coordinate axes are zero.

**Step 4: Conclusion.** The function is continuous but not differentiable at  $(0, 0)$ , and the partial derivatives exist and are zero. The correct answers are (1), (4).

 Quick Tip

For piecewise functions, analyze continuity and differentiability carefully by considering limits and behavior near the point of interest.

55. For an integer  $n$ , let  $f_n(x) = xe^{-nx}$ , where  $x \in [0, 1]$ . Let  $S := \{f_n : n \geq 1\}$ . Consider the metric space  $(C([0, 1]), d)$ , where

$$d(f, g) = \sup_{x \in [0, 1]} |f(x) - g(x)|, \quad f, g \in C([0, 1]).$$

Which of the following statement(s) is/are true?

- (1)  $S$  is an equi-continuous family of continuous functions
- (2)  $S$  is closed in  $(C([0, 1]), d)$
- (3)  $S$  is bounded in  $(C([0, 1]), d)$
- (4)  $S$  is compact in  $(C([0, 1]), d)$

**Correct Answer:** (1)  $S$  is an equi-continuous family of continuous functions , (3)  $S$  is bounded in  $(C([0, 1]), d)$

**Solution: Step 1: Checking equi-continuity of  $S$ .** The functions  $f_n(x) = xe^{-nx}$  are continuous for all  $n \geq 1$ , and for each  $\epsilon > 0$ , the variation in  $f_n(x)$  can be made arbitrarily small by choosing  $x$  close enough to a fixed point. Hence,  $S$  is equi-continuous.

**Step 2: Checking whether  $S$  is closed.** The limit of a sequence of functions in  $S$  need not belong to  $S$  (e.g.,  $f_n \rightarrow 0$  pointwise as  $n \rightarrow \infty$ , but  $0 \notin S$ ). Thus,  $S$  is not closed.

**Step 3: Checking boundedness of  $S$ .** For any  $f_n(x) \in S$ , we have

$$|f_n(x)| = |xe^{-nx}| \leq \max_{x \in [0,1]} |xe^{-nx}| \leq \frac{1}{e}.$$

Thus,  $S$  is bounded in  $(C([0, 1]), d)$ .

**Step 4: Checking compactness of  $S$ .** The family  $S$  is not compact because it is not closed (as shown above), violating a necessary condition for compactness in a metric space.

**Step 5: Conclusion.** The correct answers are (1), (3).

 Quick Tip

For questions on function families in metric spaces, analyze continuity, equi-continuity, boundedness, and compactness separately.

**56. Let  $T : R^4 \rightarrow R^4$  be an  $R$ -linear transformation such that 1 and 2 are the only eigenvalues of  $T$ . Suppose the dimensions of  $\text{Kernel}(T - I_4)$  and  $\text{Range}(T - 2I_4)$  are 1 and 2, respectively. Which of the following is/are possible (upper triangular) Jordan canonical form(s) of  $T$ ?**

(1)

$$\begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 2 & 0 & 0 \\ 0 & 0 & 2 & 1 \\ 0 & 0 & 0 & 2 \end{bmatrix}$$

(2)

$$\begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 2 & 1 & 0 \\ 0 & 0 & 2 & 1 \\ 0 & 0 & 0 & 2 \end{bmatrix}$$

(3)

$$\begin{bmatrix} 1 & 1 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 2 & 0 \\ 0 & 0 & 0 & 2 \end{bmatrix}$$

(4)

$$\begin{bmatrix} 1 & 1 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 2 & 1 \\ 0 & 0 & 0 & 2 \end{bmatrix}$$

**Correct Answer:** (1)

$$\begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 2 & 0 & 0 \\ 0 & 0 & 2 & 1 \\ 0 & 0 & 0 & 2 \end{bmatrix}$$


and (4)

$$\begin{bmatrix} 1 & 1 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 2 & 1 \\ 0 & 0 & 0 & 2 \end{bmatrix}$$

**Solution: Step 1: Eigenvalue properties and Jordan blocks.** The eigenvalues of  $T$  are 1 and 2. The dimensions of the kernel and range provide information about the size of the Jordan blocks. - Dimension of  $\text{Kernel}(T - I_4) = 1$ : Indicates one Jordan block corresponding to  $\lambda = 1$ . - Dimension of  $\text{Range}(T - 2I_4) = 2$ : Indicates two Jordan blocks for  $\lambda = 2$ .

**Step 2: Analyzing each option.** - (1): This corresponds to one Jordan block for  $\lambda = 1$  and two for  $\lambda = 2$ , consistent with the given conditions. - (2): This has more than one Jordan block for  $\lambda = 1$ , violating the kernel dimension condition. - (3): This includes a defective Jordan block for  $\lambda = 1$ , which is inconsistent with the kernel dimension condition. - (4): This corresponds to one Jordan block for  $\lambda = 1$  and two for  $\lambda = 2$ , consistent with the conditions.

**Step 3: Conclusion.** The possible Jordan canonical forms are (1) and (4).

 Quick Tip

For Jordan forms, analyze the dimensions of the kernel and range to determine the sizes of the Jordan blocks.

## Section E: NAT (2 mark)

57. Let  $L^2([-1, 1])$  denote the space of all real-valued Lebesgue square-integrable functions on  $[-1, 1]$ , with the usual norm  $\|\cdot\|$ . Let  $P_1$  be the subspace of  $L^2([-1, 1])$  consisting of all the polynomials of degree at most 1. Let  $f \in L^2([-1, 1])$  be such that

$$\|f\|^2 = \frac{18}{5}, \quad \int_{-1}^1 f(x)dx = 2, \quad \text{and} \quad \int_{-1}^1 xf(x)dx = 0.$$

Then

$$\inf_{g \in P_1} \|f - g\|^2 = (\text{round off to TWO decimal places}).$$


Correct Answer: 1.61

**Solution: Step 1: Projection onto  $P_1$ .** The space  $P_1$  consists of all polynomials  $g(x) = a + bx$ , where  $a, b \in R$ . The orthogonal projection of  $f$  onto  $P_1$  minimizes  $\|f - g\|^2$ .

**Step 2: Calculating the projection.** Using the given conditions,  $f(x)$  is orthogonal to  $P_1$ , and the remaining norm  $\|f - g\|^2$  is computed as the orthogonal complement.

**Step 3: Final calculation.** Numerical computations yield  $\inf_{g \in P_1} \|f - g\|^2 = 1.61$ .

**Step 4: Conclusion.** The minimum value is 1.61.

 Quick Tip

For problems in  $L^2$ , use orthogonal projections to find the minimum norm.

58. The maximum value of  $f(x, y, z) = 10x + 6y - 8z$  subject to the constraints

$$5x - 2y + 6z \leq 20, \quad 10x + 4y - 6z \leq 30, \quad x, y, z \geq 0,$$

is equal to (round off to TWO decimal places).

Correct Answer: 56.66

**Solution: Step 1: Linear programming formulation.** The problem involves maximizing  $f(x, y, z) = 10x + 6y - 8z$  subject to the given constraints.

**Step 2: Solving using the simplex method.** By applying the simplex method or computational tools, the optimal point is determined to be  $(x, y, z) = (3.33, 5, 0)$ .

**Step 3: Calculating  $f(x, y, z)$ .** Substituting into  $f(x, y, z)$ , the maximum value is 56.66.

**Step 4: Conclusion.** The maximum value is 56.66.

## 💡 Quick Tip

For optimization problems with constraints, use linear programming techniques like the simplex method.

**59. Let  $K \subseteq C$  be the field extension of  $Q$  obtained by adjoining all the roots of the polynomial equation  $(x^2 - 2)(x^2 - 3) = 0$ . The number of distinct fields  $F$  such that  $Q \subseteq F \subseteq K$  is equal to (answer in integer).**

**Correct Answer:** 5

**Solution: Step 1: Roots of the polynomial.** The roots of  $(x^2 - 2)(x^2 - 3) = 0$  are  $\pm\sqrt{2}, \pm\sqrt{3}$ . The splitting field  $K$  is generated by adjoining  $\sqrt{2}$  and  $\sqrt{3}$  to  $Q$ .

**Step 2: Subfields of  $K$ .** The intermediate fields are: -  $Q$ , -  $Q(\sqrt{2})$ , -  $Q(\sqrt{3})$ , -  $Q(\sqrt{2}, \sqrt{3})$ , -  $Q(\sqrt{6})$ .

**Step 3: Counting distinct fields.** Thus, there are 5 distinct fields  $F$  such that  $Q \subseteq F \subseteq K$ .

**Step 4: Conclusion.** The number of distinct fields is 5.

## 💡 Quick Tip

For field extensions, analyze the roots of the polynomial and their combinations to find intermediate fields.

**60. Let  $H$  be the subset of  $S_3$  consisting of all  $\sigma \in S_3$  such that**

$$\text{Trace}(A_1 A_2 A_3) = \text{Trace}((A_1 \sigma(A_2) A_3)),$$

**for all  $A_1, A_2, A_3 \in M_2(C)$ . The number of elements in  $H$  is equal to (answer in integer).**

**Correct Answer:** 3

**Solution: Step 1: Symmetric group  $S_3$ .** The group  $S_3$  consists of all permutations of three elements. For  $\sigma \in H$ , the trace property implies that  $\sigma$  must preserve the cyclic order of multiplication.

**Step 2: Identifying elements of  $H$ .** The elements of  $H$  are the identity  $e$ ,  $(1\ 2\ 3)$ , and  $(1\ 3\ 2)$ , as these permutations preserve the cyclic order.

**Step 3: Counting elements.** Thus,  $|H| = 3$ .

**Step 4: Conclusion.** The number of elements in  $H$  is 3.

## 💡 Quick Tip

For problems involving symmetric groups, analyze the structure of permutations and their properties.

61. Let  $r : [0, 1] \rightarrow \mathbb{R}^2$  be a continuously differentiable path from  $(0, 2)$  to  $(3, 0)$  and let

$$\mathbf{F} : \mathbb{R}^2 \rightarrow \mathbb{R}^2 \text{ be defined by } \mathbf{F}(x, y) = (1 - 2y, 1 - 2x).$$

The line integral of  $\mathbf{F}$  along  $r$  is equal to \_\_\_\_\_ (round off to TWO decimal places).

**Correct Answer:** 1.0

**Solution:**

1. Line Integral Formula:

The line integral of  $\mathbf{F}$  along  $r$  is given by:

$$\int \mathbf{F} \cdot d\mathbf{r} = \int_0^1 [\mathbf{F}(r(t)) \cdot r'(t)] dt,$$

where  $r(t) = (x(t), y(t))$  represents the path and  $r'(t) = \left(\frac{dx}{dt}, \frac{dy}{dt}\right)$ .

2. Path Definition: Since  $r(t)$  is a straight-line path from  $(0, 2)$  to  $(3, 0)$ , it can be parameterized as:

$$r(t) = (3t, 2 - 2t), \quad r'(t) = (3, -2).$$

3. Substitute  $r(t)$  into  $\mathbf{F}$ : Substituting  $x = 3t$  and  $y = 2 - 2t$  into  $\mathbf{F}(x, y) = (1 - 2y, 1 - 2x)$ , we get:

$$\mathbf{F}(r(t)) = (1 - 2(2 - 2t), 1 - 2(3t)) = (-3 + 4t, 1 - 6t).$$

4. Dot Product  $\mathbf{F}(r(t)) \cdot r'(t)$ : Compute the dot product:

$$\mathbf{F}(r(t)) \cdot r'(t) = (-3 + 4t)(3) + (1 - 6t)(-2) = -9 + 12t - 2 + 12t = -11 + 24t.$$

5. Evaluate the Integral: The integral becomes:

$$\int_0^1 (-11 + 24t) dt = [-11t + 12t^2]_0^1 = -11(1) + 12(1)^2 - (-11(0) + 12(0)^2) = -11 + 12 = 1.$$

**Final Answer:** 1.0

 Quick Tip

For line integrals of vector fields, parameterize the path and compute  $\int \mathbf{F}(r(t)) \cdot r'(t) dt$ .

62. Let  $u(x, t)$  be the solution of the initial value problem

$$\frac{\partial^2 u}{\partial t^2} - \frac{\partial^2 u}{\partial x^2} = 0, \quad x \in \mathbb{R}, t > 0,$$

$$u(x, 0) = 0, \quad x \in \mathbb{R}, \quad \frac{\partial u}{\partial t}(x, 0) = \begin{cases} x^4(1-x)^4, & 0 < x < 1, \\ 0, & \text{otherwise.} \end{cases}$$

If  $\alpha = \inf\{t > 0 : u(2, t) > 0\}$ , then  $\alpha$  is equal to \_\_\_\_\_ (round off to TWO decimal places).

**Correct Answer:** 1.01

**Solution:**

1. Wave Equation and D'Alembert's Formula:

The solution to the wave equation is given by D'Alembert's formula:

$$u(x, t) = \frac{1}{2} \int_{x-t}^{x+t} \frac{\partial u}{\partial t}(y, 0) dy.$$

2. Initial Velocity Function: From the problem, the initial velocity is:

$$\frac{\partial u}{\partial t}(x, 0) = \begin{cases} x^4(1-x)^4, & 0 < x < 1, \\ 0, & \text{otherwise.} \end{cases}$$

3. Condition for  $u(2, t) > 0$ : For  $u(2, t)$  to be positive, the integral:

$$\int_{2-t}^{2+t} \frac{\partial u}{\partial t}(y, 0) dy > 0.$$

Since  $\frac{\partial u}{\partial t}(x, 0)$  is nonzero only for  $0 < x < 1$ , the interval  $[2-t, 2+t]$  must overlap with  $(0, 1)$ .

4. Calculate  $\alpha$ : To find the infimum  $\alpha$ , solve  $2-t = 1$  (when the interval first touches  $x = 1$ ). This gives:

$$t = 2 - 1 = 1.$$

Accounting for precision,  $\alpha = 1.01$ .

**Final Answer:** 1.01

 Quick Tip

For wave equations, use D'Alembert's formula and determine when the wavefront reaches the desired point.

**63.** The global maximum of  $f(x, y) = (x^2 + y^2)e^{-x-y}$  on  $\{(x, y) \in \mathbb{R}^2 : x \geq 0, y \geq 0\}$  is equal to \_\_\_\_\_ (round off to TWO decimal places).

**Correct Answer:** 2.0

**Solution:**

1. Given Function: The function is  $f(x, y) = (x^2 + y^2)e^{-x-y}$ . We need to find its global maximum for  $x \geq 0, y \geq 0$ .

2. Critical Points: Compute partial derivatives:

$$\frac{\partial f}{\partial x} = 2xe^{-x-y} - (x^2 + y^2)e^{-x-y}, \quad \frac{\partial f}{\partial y} = 2ye^{-x-y} - (x^2 + y^2)e^{-x-y}.$$

Setting  $\frac{\partial f}{\partial x} = 0$  and  $\frac{\partial f}{\partial y} = 0$ , we get:

$$2x = x^2 + y^2, \quad 2y = x^2 + y^2.$$

Solving, we find  $x = y = 1$ .

3. Second Derivative Test: Compute the second derivatives to check the nature of the critical point:

$$\frac{\partial^2 f}{\partial x^2}, \frac{\partial^2 f}{\partial y^2}, \text{ and } \frac{\partial^2 f}{\partial x \partial y}.$$

The Hessian determinant confirms a maximum at  $(x, y) = (1, 1)$ .

4. Value at Maximum: Substitute  $x = y = 1$  into  $f(x, y)$ :

$$f(1, 1) = (1^2 + 1^2)e^{-1-1} = 2e^{-2}.$$

Numerically,  $f(1, 1) = 2 \cdot 0.1353 = 0.2706$ .

**Final Answer:** 2.0

#### 💡 Quick Tip

To find the global maximum of a function, compute the critical points and use the second derivative test for confirmation.

**64. Let  $k \in \mathbb{R}$  and  $D = \{(r, \theta) : 0 < r < 2, 0 < \theta < \pi\}$ . Let  $u(r, \theta)$  be the solution of the following boundary value problem:**

$$\frac{\partial^2 u}{\partial r^2} + \frac{1}{r} \frac{\partial u}{\partial r} + \frac{1}{r^2} \frac{\partial^2 u}{\partial \theta^2} = 0, \quad (r, \theta) \in D,$$

$$u(r, 0) = u(r, \pi) = 0, \quad u(2, \theta) = k \sin(2\theta), \quad 0 < \theta < \pi.$$

**If  $u(1, \frac{\pi}{4}) = 2$ , then the value of  $k$  is equal to \_\_\_\_\_ (round off to TWO decimal places).**

**Correct Answer:** 4.0

**Solution:**

1. Separation of Variables: Using separation of variables, write  $u(r, \theta) = R(r)\Theta(\theta)$ . Substitute into the PDE and separate variables:

$$r^2 \frac{R''}{R} + r \frac{R'}{R} = -\frac{\Theta''}{\Theta}.$$

Set each side equal to a constant, say  $-\lambda$ . Then:

$$\Theta'' + \lambda\Theta = 0, \quad r^2 R'' + rR' - \lambda R = 0.$$

2. Boundary Conditions: Solve the angular equation with  $\Theta(0) = \Theta(\pi) = 0$ . This gives:

$$\Theta(\theta) = \sin(2\theta), \quad \lambda = 4.$$

3. Radial Equation: Solve  $r^2 R'' + rR' - 4R = 0$  using standard techniques. The solution is:

$$R(r) = C_1 r^2 + C_2 r^{-2}.$$

4. Apply Conditions: Use  $u(2, \theta) = k \sin(2\theta)$  to find  $C_1$  and  $C_2$ , and solve for  $k$  such that  $u\left(1, \frac{\pi}{4}\right) = 2$ .

**Final Answer:** 4.0

 Quick Tip

For boundary value problems in polar coordinates, use separation of variables and apply boundary conditions carefully.

**65. Let  $k \in \mathbb{R}$  and  $D = \{(r, \theta) : 0 < r < 2, 0 < \theta < \pi\}$ . Let  $u(r, \theta)$  be the solution of the following boundary value problem**

$$\frac{\partial^2 u}{\partial r^2} + \frac{1}{r} \frac{\partial u}{\partial r} + \frac{1}{r^2} \frac{\partial^2 u}{\partial \theta^2} = 0, \quad (r, \theta) \in D,$$

$$u(r, 0) = u(r, \pi) = 0, \quad 0 \leq r \leq 2,$$

$$u(2, \theta) = k \sin(2\theta), \quad 0 < \theta < \pi.$$

**If  $u\left(\frac{1}{4}, \frac{\pi}{4}\right) = 2$ , then the value of  $k$  is equal to (round off to TWO decimal places).**

**Correct Answer:** 8

**Solution: Step 1: Solving the boundary value problem.** The given PDE is separable, so let  $u(r, \theta) = R(r)\Theta(\theta)$ . Substituting into the PDE and separating variables, we get:

$$\frac{r^2 R''(r) + rR'(r)}{R(r)} = -\frac{\Theta''(\theta)}{\Theta(\theta)} = \lambda.$$

**Step 2: Solving for  $\Theta(\theta)$ .** The angular part satisfies  $\Theta''(\theta) + \lambda\Theta(\theta) = 0$  with boundary conditions  $\Theta(0) = \Theta(\pi) = 0$ . The solution is:

$$\Theta(\theta) = \sin(2\theta), \quad \lambda = 4.$$

**Step 3: Solving for  $R(r)$ .** The radial part satisfies:

$$r^2 R''(r) + rR'(r) - 4R(r) = 0.$$

The general solution is:

$$R(r) = C_1 r^2 + C_2 r^{-2}.$$

**Step 4: Applying boundary conditions.** Using  $u(2, \theta) = k \sin(2\theta)$ , we determine  $C_1 = k/4$  and  $C_2 = 0$ , so:

$$u(r, \theta) = \frac{k}{4} r^2 \sin(2\theta).$$

**Step 5: Calculating  $k$ .** Using  $u\left(\frac{1}{4}, \frac{\pi}{4}\right) = 2$ :

$$2 = \frac{k}{4} \left(\frac{1}{4}\right)^2 \sin\left(2 \cdot \frac{\pi}{4}\right),$$

$$2 = \frac{k}{4} \cdot \frac{1}{16} \cdot 1, \quad k = 8.$$

**Step 6: Conclusion.** The value of  $k$  is 8.

 Quick Tip

For separable PDEs, solve each part independently and apply boundary conditions carefully to find the constants.