

Chapter 7Alternating Current

Voltage or current that changes its sign periodically with time is called alternating.

Most common form : sinusoidal AC.

Why AC ?

1. Easily stepped up / down by transformers.
2. Long - distance transmission with low losses.
3. AC generators are simpler than DC ones.

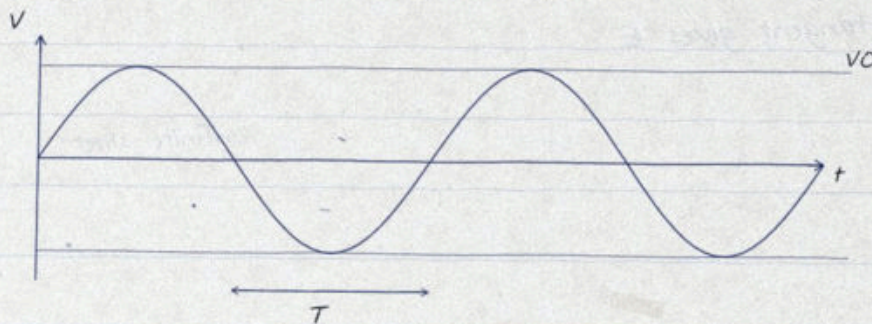


Fig. sinusoidal AC voltage waveform

Topics ahead

RMS ; R , L , C circuits ; LCR ; transformer.

## AC Source - Instantaneous V & I

### Sinusoidal form

An AC source delivers an EMF that varies as :

$$V(t) = V_0 \sin \omega t$$

<-  $V_0$  = peak  
<- voltage

$$I(t) = I_0 \sin (\omega t + \phi)$$

<-  $\phi$  = phase  
<- difference

### Useful quantities

Angular frequency :  $\omega = 2\pi f$

Time period :  $T = 1/f = 2\pi/\omega$

In India :  $f = 50 \text{ Hz}$ ,  $\omega = 100\pi \text{ rad/s}$ .

### Average over full cycle

$\int_0^T V dt$  over 0 to  $T = 0$  ; same for  $I$ .

Mean of pure sine over one cycle is zero ;

so we use half-cycle mean or RMS instead.

### Phase relations (coming up)

Pure R :  $V, I$  in phase ( $\phi = 0$ )

Pure L :  $V$  leads  $I$  by  $\pi/2$

Pure C :  $V$  lags  $I$  by  $\pi/2$

LCR : phase depends on  $X_L$  vs  $X_C$ .

## Mean (Average) Value over Half Cycle

For positive half of cycle (0 to  $T/2$ ) :

$$I_{avg} = (1/(T/2)) \int_0^{T/2} I_0 \sin \omega t \, dt$$

$$\text{Limits : } t = 0 \text{ to } t = T/2.$$

$$= (2 I_0 / T) [-\cos \omega t / \omega] \text{ from } 0 \text{ to } T/2$$

$$= (2 I_0 / T) \cdot (2 / \omega)$$

$$= (2 I_0 / T) \cdot (T / \pi)$$

$$I_{avg} = 2 I_0 / \pi \quad 0.637 I_0$$

← half - cycle  
← mean

$$\text{Similarly : } V_{avg} = 2 V_0 / \pi \quad 0.637 V_0.$$

### Why this\* matters

DC ammeters cannot measure AC because mean over full cycle is ~~not zero~~ zero. Hot - wire meters / RMS meters are used instead.

Hence the RMS value - next page.

## RMS Value (Root - Mean - Square)

### Definition -

RMS current = steady DC current that produces the same heat in  $R$  over the same time.

Heat in  $R$  over one cycle :

$$H = \int_0^T I^2 R dt \quad \text{from } 0 \text{ to } T$$

$$= R I_0^2 \int_0^T \sin^2 \omega t dt$$

$$\text{use } \sin^2 x = (1 - \cos 2x) / 2 :$$

$$= R I_0^2 \cdot T / 2$$

Equate to  $I_{\text{rms}}^2 R T :$

$$I_{\text{rms}}^2 = I_0^2 / 2$$

$$I_{\text{rms}} = I_0 / \sqrt{2} \quad 0.707 I_0$$

<- key result  
<- for sinusoid

Similarly  $V_{\text{rms}} = V_0 / \sqrt{2}$ .

Indian mains : 220 V is  $V_{\text{rms}}$ , so  $V_0 = 311$  V.

## AC Through Pure Resistor

Source  $V = V_0 \sin \omega t$  across resistance  $R$ .

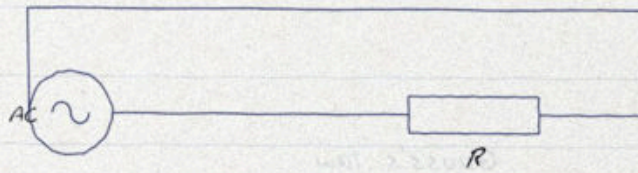


Fig. AC source + pure resistor

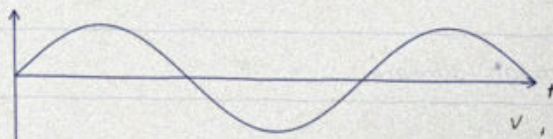
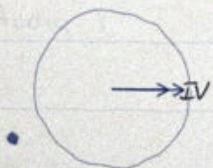
### Derivation

$$\begin{aligned} \text{KVL } \therefore V &= I R \rightarrow I = V/R \\ &= (V_0/R) \sin \omega t \end{aligned}$$

$$I = I_0 \sin \omega t ; I_0 = V_0 / R$$

$\phi = 0$   
(in phase)

phasor



$V, I$  in phase

## AC Through Pure Inductor

Source  $V = V_0 \sin \omega t$  across an ideal inductor of inductance  $L$  (no resistance).

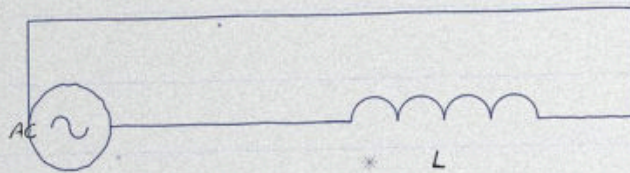


Fig. AC across pure inductor

### Derivation

$$\text{Self-induced EMF} : E_L = -L \frac{dI}{dt}$$

$$\text{KVL} : V - L \frac{dI}{dt} = 0 \rightarrow L \frac{dI}{dt} = V$$

$$\frac{dI}{dt} = \left(\frac{V_0}{L}\right) \sin \omega t$$

$$\text{Integrate} : I = -\left(\frac{V_0}{\omega L}\right) \cos \omega t$$

$$= \left(\frac{V_0}{\omega L}\right) \sin \left(\omega t - \frac{\pi}{2}\right)$$

$$I = I_0 \sin \left(\omega t - \frac{\pi}{2}\right)$$

$\leftarrow I$  lags  $V$   
 $\leftarrow$  by  $\pi/2$

$$X_L = \omega L ; I_0 = \frac{V_0}{X_L}$$

## Inductive Reactance & Phasor (L)

### Inductive reactance $X_L$

$$X_L = \omega L = 2\pi f L$$

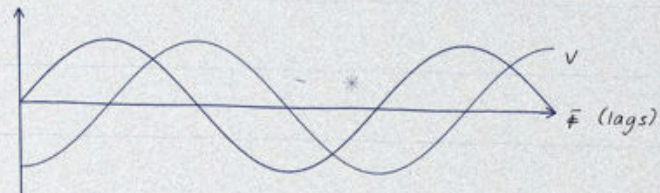
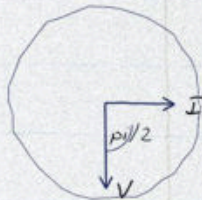
← unit : ohm

$X_L$  grows with frequency.

DC ( $f = 0$ ) :  $X_L = 0 \rightarrow L$  acts as plain wire.

High  $f$  :  $X_L$  large  $\rightarrow L$  ~~passes~~ blocks AC.

phasor diagram



### Power in pure L (average)

$$P = V I = V_0 I_0 \sin \omega t \cos \omega t$$

$$= (V_0 I_0 / 2) \sin 2 \omega t$$

Average over full cycle = 0  $\rightarrow$  no real power.

L is a wattless component.

## AC Through Pure Capacitor

Source  $V = V_0 \sin \omega t$  across capacitor  $C$ .

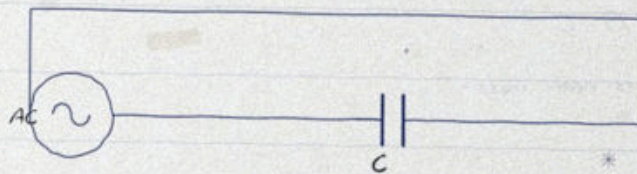


Fig. AC across pure capacitor

### Derivation

$$\text{Charge on } C : q = C V = C V_0 \sin \omega t$$

$$I = dq / dt = C V_0 \omega \cos \omega t$$

$$= C V_0 \omega \sin (\omega t + \pi/2)$$

$$I = I_0 \sin (\omega t + \pi/2)$$

$\leftarrow I$  leads  $V$   
 $\leftarrow$  by  $\pi/2$

$$X_C = 1 / (\omega C) ; I_0 = V_0 / X_C$$

$\leftarrow$  capacitive  
 $\leftarrow$  reactance

DC ( $f = 0$ ) :  $X_C \rightarrow$  infinity ( $C$  blocks DC).

High  $f$  :  $X_C$  small  $\rightarrow$   $C$  passes AC easily.

Average power in pure  $C$  is also zero (wattless).

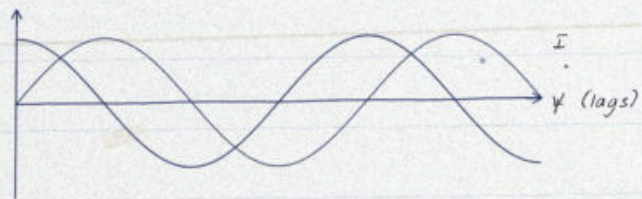
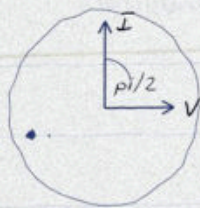
## Capacitive Reactance & Phasor (C)

$$X_C = 1 / (\omega C) = 1 / (2 \pi f C)$$

← unit : ohm

$X_C$  is INVERSE to omega ; doubling  $f$  halves  $X_C$ .

phasor (C)



### Comparison R - L - C

R :  $\phi = 0$  (in phase)

L :  $\phi = + \pi/2$  (V leads I)

C :  $\phi = - \pi/2$  (V lags I)

Mnemonic : ELI the ICE man - !

## Series LCR Circuit - Setup

$R$ ,  $L$  and  $C$  connected in series across an AC source  $V = V_0 \sin \omega t$ .

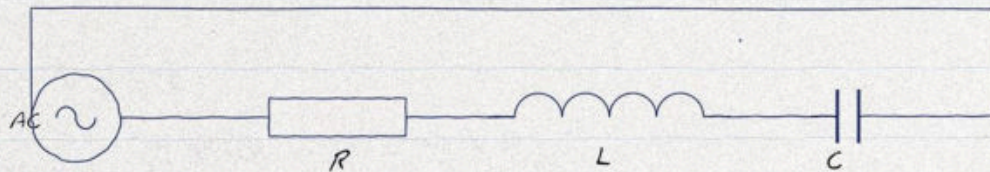


Fig. series LCR circuit

Same current, different  $V$  across each

Let  $I(t) = I_0 \sin(\omega t - \phi)$ .

$V_R = I R$  (in phase with  $I$ )

$V_L = I X_L$  (leads  $I$  by  $\pi/2$ )

$V_C = I X_C$  (lags  $I$  by  $\pi/2$ )

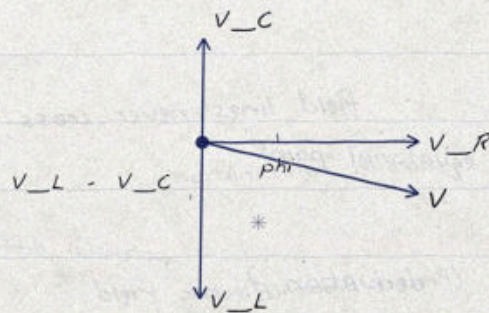
Source  $V$  must equal vector sum of all three.

$V = V_R + V_L + V_C$  (phasor sum)

Next page : phasor derivation of impedance  $Z$ .

## Phasor Derivation of Impedance Z

### Phasor diagram



### Magnitudes

$$V^2 = V_R^2 + (V_L - V_C)^2$$

$$= I^2 [ R^2 + (X_L - X_C)^2 ]$$

Define impedance Z by  $V = I Z$  :

$$Z = \sqrt{R^2 + (X_L - X_C)^2}$$

<- unit : ohm

$$\tan \phi = (X_L - X_C) / R$$

## Cases & Sign of phi

### Three regimes

- ①  $X_L > X_C$  : inductive circuit  
 $\phi > 0 \rightarrow V$  leads  $I$  (like pure L).
- ②  $X_L < X_C$  : capacitive circuit  
 $\phi < 0 \rightarrow V$  lags  $I$  (like pure C).
- ③  $X_L = X_C$  : RESONANCE  
 $\phi = 0$  ;  $Z = R$  (purely resistive).

### Peak current

$$I_0 = V_0 / Z$$

$\leftarrow$  and similarly

$$\leftarrow I_{\text{rms}} = V_{\text{rms}} / Z$$

### Numeric example

$$R = 30 \text{ ohm}, X_L = 60 \text{ ohm}, X_C = 20 \text{ ohm} :$$

$$X_L - X_C = 40 \text{ ohm}$$

$$Z = \sqrt{30^2 + 40^2} = 50 \text{ ohm}$$

$$\tan \phi = 40 / 30 = 4 / 3$$

$$\phi = 53 \text{ deg (V leads I)}$$

$$\text{Cross-check : } \cos \phi = R/Z = 30/50 = 0.6$$

## Resonance in Series LCR

### Condition

$$X_L = X_C \rightarrow \omega L = 1 / (\omega C)$$

$$\omega_0 = 1 / \sqrt{LC}$$

← resonant  
← angular freq

$$f_0 = 1 / (2\pi \sqrt{LC})$$

### At resonance

$$Z_{\min} = R \quad (\text{smallest possible})$$

$$I_{\max} = V_0 / R$$

$\phi = 0 \rightarrow V, I$  in phase (pure resistive).

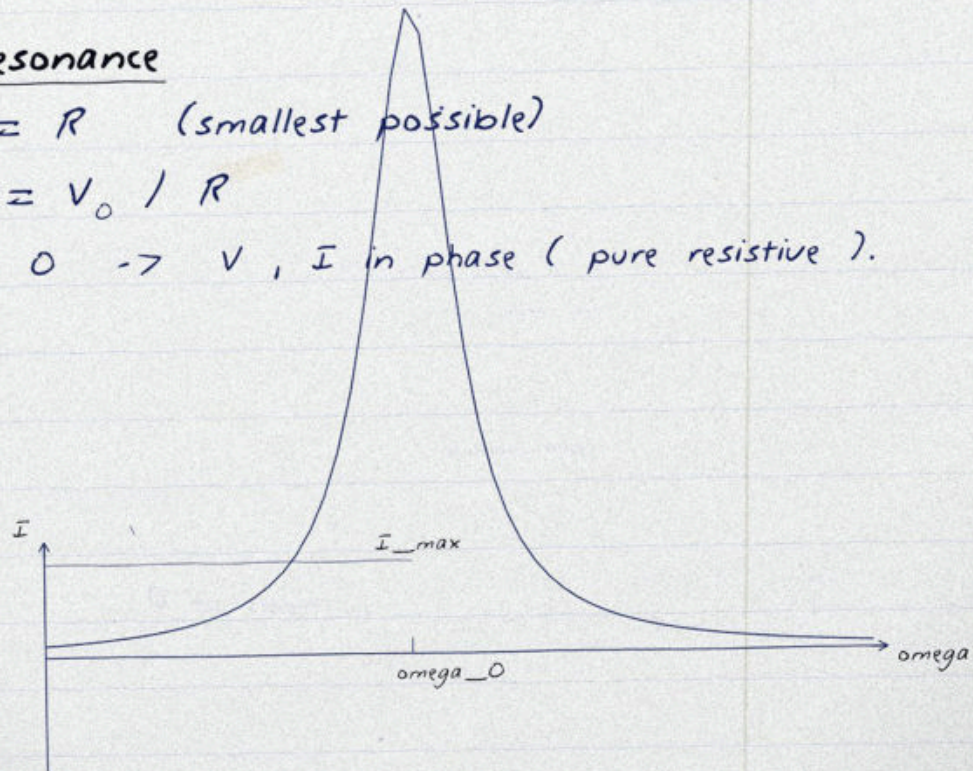


Fig.  $I$  vs  $\omega$  - resonance curve

Sharpness of peak  $\rightarrow$   $Q$  - factor (next page).

## Sharpness & Q - Factor

### Bandwidth

Bandwidth =  $2 \Delta \omega$  = range of  $\omega$  over which  $I$  drops to  $I_{\max} / \sqrt{2}$  (half - power points).

At these points :  $\omega L - 1/(\omega C) = \pm R$

$\Delta \omega = R / (2L)$  (half - \* width)

### Quality factor Q

$$Q = \omega_0 / (2 \Delta \omega) = \omega_0 L / R$$

$$Q = 1 / (\omega_0 R C) = (1 / R) \sqrt{L / C}$$

C - key  
C - res

### Meaning

High Q : sharp peak  $\rightarrow$  good selectivity  
(radio tuning).

Low Q : broad peak  $\rightarrow$  poor selectivity.

High Q needs small R and ~~small~~ large L.

Q is dimensionless ; typical radio Q 100 .

## Power in AC Circuits

### Instantaneous power

$$p(t) = V(t) \cdot I(t)$$

$$= V_0 I_0 \sin \omega t \sin (\omega t - \phi)$$

Use  $\sin A \sin B = (1/2)[\cos(A-B) - \cos(A+B)]$  :

$$p(t) = (V_0 I_0 / 2) [\cos \phi - \cos(2\omega t - \phi)]$$

### Average power

Average of  $\cos(2\omega t - \phi)$  over one cycle = 0.

$$P_{avg} = (V_0 I_0 / 2) \cos \phi$$

$$P_{avg} = V_{rms} I_{rms} \cos \phi$$

<- this is the  
<- real power

### Apparent vs real power

Apparent :  $V_{rms} I_{rms}$  (unit : V . A)

Real :  $V_{rms} I_{rms} \cos \phi$  (unit : W) .

Difference is stored / returned by L and C.

Ratio  $\cos \phi$  : power factor.

## Power Factor & Wattless Current

### Power factor $\cos \phi$

$$\cos \phi = R / Z$$

← From phasor  
← triangle

Pure R :  $\cos \phi = 1$  → full power.

Pure L or C :  $\cos \phi = 0$  →  $P_{avg} = 0$ .

LCR :  $0 < \cos \phi < 1$ .

### Wattless current

Component of  $I$  that is perpendicular to  $V$  in the phasor diagram does NO net work.

$$I_{real} = I \cos \phi \quad (\text{in phase with } V)$$

$$I_{wattless} = I \sin \phi \quad (\text{perpendicular to } V)$$

### Why power factor matters

① Low  $\cos \phi$  → large  $I$  for same  $P$  :  
more  $I$  →  $R$  loss in transmission lines.

② Industry uses capacitor banks to  
~~decrease~~ improve  $\cos \phi$  to 0.95 .  
(Cancels inductive lag of motors.)

## LC Oscillations - Setup

Charged capacitor  $C$  is connected to a pure inductor  $L$  (no resistance).

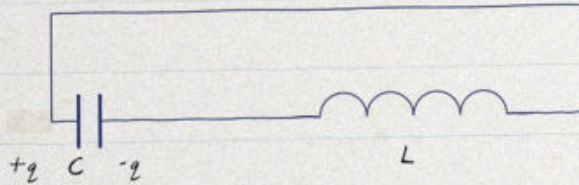


Fig. LC tank circuit (ideal)

### Equation of motion

$$V_C = V_L \rightarrow q/C = -L dI/dt$$

$$I = dq/dt \rightarrow L d^2q/dt^2 + q/C = 0$$

$$d^2q/dt^2 + (1/LC) q = 0$$

<- SHM in  $q$

\* Compare with  $x'' + \omega^2 x = 0$  :

$$\omega = 1 / \text{sqrt}(LC)$$

<- natural  
<- frequency

## LC Oscillations - Energy

### Solutions

$$q(t) = q_0 \cos \omega t$$

$$i(t) = dq/dt = -q_0 \omega \sin \omega t$$

$$i_0 = q_0 \omega = q_0 / \sqrt{LC}$$

### Energy at any t

$$U_E = q^2 / (2C) \quad (\text{in } C)$$

$$U_B = (1/2) L i^2 \quad (\text{in } L)$$

$$\text{Total } U = q_0^2 / (2C) = \text{const.}$$

Energy sloshes between C and L like KE and PE of a SHM. At any instant, total is conserved.

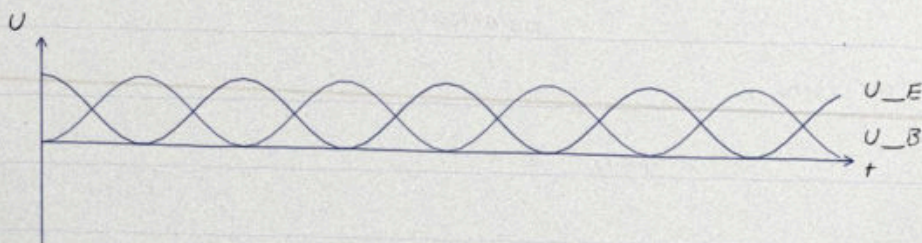


Fig.  $U_E$  and  $U_B$  exchange ; total constant

Real circuits :  $R$  causes damping (heat loss).

## Transformer - Construction

Static device for changing AC voltage level by mutual induction between two coils on a common soft-iron core.

### Parts

- ① Primary coil - connected to AC source.
- ② Secondary coil - delivers output.
- ③ Soft iron core - laminated ; carries common flux through both coils.

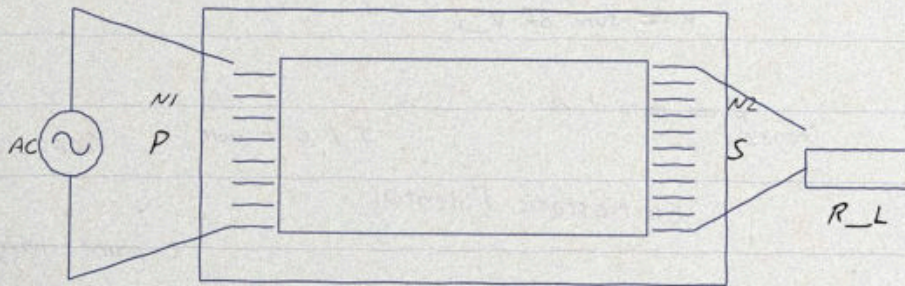


Fig. transformer : P + S coils on soft-iron core

Laminations  $\rightarrow$  reduce eddy currents in core.

## Transformer - Working

### Flux is common

Same flux  $\phi(t)$  links every turn of P and S (no leakage, ideal case).

$$\text{EMF in P} : E_1 = -N_1 d\phi / dt$$

$$\text{EMF in S} : E_2 = -N_2 d\phi / dt$$

Divide :

$$\boxed{V_2 / V_1 = N_2 / N_1} \quad \leftarrow \text{turns ratio}$$

### Ideal transformer (no losses)

$$\text{Power in} = \text{Power out} : V_1 I_1 = V_2 I_2$$

$$\boxed{I_2 / I_1 = N_1 / N_2} \quad \leftarrow \begin{array}{l} I \text{ reciprocal} \\ \leftarrow \text{of } V \end{array}$$

### Step - up vs step - down

$$\text{Step - up} : N_2 > N_1 \rightarrow V_2 > V_1, I_2 < I_1.$$

$$\text{Step - down} : N_2 < N_1 \rightarrow V_2 < V_1, I_2 > I_1.$$

High V is used to transmit ; low V to ~~waste~~ use .

Power line : step - up at plant , step - down at home.

## Energy Losses in Transformers

### Four main losses

- ① Copper loss -  $I^2 R$  in coil windings  
Remedy : use thick low -  $R$  copper wire.
- ② Iron loss - in the core . Two parts :
  - (a) Hysteresis : energy lost per  $B - H$  cycle.  
Remedy : use soft iron (narrow loop).
  - (b) Eddy currents : swirling  $I$  in core .  
Remedy : laminate core into thin sheets.
- ③ Flux leakage - not all flux links  $S$ .  
Remedy : wind both coils on the same limb.
- ④ Humming - magnetostriction of core  
(small mechanical loss as audible sound).

### Efficiency

$$\eta = P_{out} / P_{in} \times 100 \%$$

Typical real transformer :  $\eta = 95 - 99 \%$ .

Highest efficiency device in electrical eng. ?

(No moving parts  $\rightarrow$  small frictional loss.)

## Long - Distance Transmission

Power generated at  $V_{gen}$  ( 11 kV ).

Stepped up to 220 kV (or more) before being sent through transmission lines.

### Why high V ?

Power transmitted :  $P = V I$

Line loss :  $P_{loss} = I^2 R = (P / V)^2 R$

Higher V  $\rightarrow$  smaller I  $\rightarrow$  much smaller  $I^2 R$  loss.

Loss scales as  $1 / V^2$ .

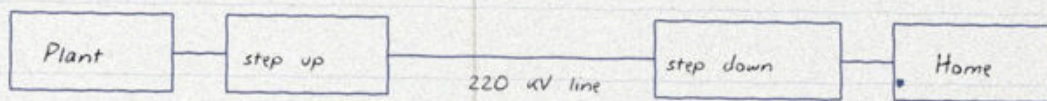


Fig. step-up before line ; step-down at user

### Trade - off

Higher V needs better insulation , taller pylons.

Balance line loss vs cost of high - V hardware.

## Worked Example I : Resonance

Problem :  $L = 2.0 \text{ H}$ ,  $C = 32 \text{ } \mu\text{F}$ ,  $R = 10 \text{ ohm}$ ,  
 $V_{\text{rms}} = 230 \text{ V}$ . Find :

(a)  $f_0$ , (b)  $I_{\text{max}}$  at resonance, (c) Q factor.

### (a) Resonant frequency

$$f_0 = 1 / (2 \pi \sqrt{L C})$$

$$\sqrt{L C} = \sqrt{2.0 \cdot 32 \times 10^{-6}}$$

$$= \sqrt{6.4 \times 10^{-5}} = 8.0 \times 10^{-3} \text{ s}$$

$$f_0 = 1 / (2 \pi \cdot 8.0 \times 10^{-3})$$

$$19.9 \text{ Hz}$$

### (b) $I_{\text{max}}$

At resonance  $Z = R = 10 \text{ ohm}$

$$I_{\text{rms}} = V_{\text{rms}} / R = 230 / 10 = 23 \text{ A}$$

$$I_0 = \sqrt{2} \cdot I_{\text{rms}} = 32.5 \text{ A}$$

### (c) Q factor

$$Q = (1/R) \sqrt{L/C}$$

$$L/C = 2.0 / (32 \times 10^{-6}) = 6.25 \times 10^4$$

$$\sqrt{L/C} = 250 \text{ ohm}$$

$$Q = 250 / 10 = 25$$

Bandwidth  $f_0 / Q = 19.9 / 25 = 0.8 \text{ Hz}$ .

Very sharp peak  $\rightarrow$  selective circuit.

## Worked Example II : Power

Problem : 220 V AC source feeds  $R = 100$  ohm in series with  $L = 0.5$  H at  $f = 50$  Hz . Find :  
 (a)  $X_L$  , (b)  $Z$  , (c)  $I_{rms}$  ; (d)  $P_{avg}$ .

(a)  $X_L$

$$X_L = 2 \pi f L = 2 \cdot 3.14 \cdot 50 \cdot 0.5$$

$$157 \text{ ohm}$$

(b)  $Z$

$$Z = \sqrt{R^2 + X_L^2}$$

$$= \sqrt{100^2 + 157^2}$$

$$= \sqrt{10000 + 24649}$$

$$186 \text{ ohm}$$

(c)  $I_{rms}$

$$I_{rms} = 220 / 186 \quad 1.18 \text{ A}$$

(d)  $P_{avg}$

$$\cos \phi = R / Z = 100 / 186 \quad 0.54$$

$$P_{avg} = V_{rms} I_{rms} \cos \phi$$

$$= 220 \cdot 1.18 \cdot 0.54$$

$$140 \text{ W}$$

Note : apparent power = 220 . 1.18      260 V . A.

## Worked Example III : Transformer

Problem : Step-down transformer  $N_1 = 2000$ ,  $N_2 = 100$ . Primary connected to 220 V, 50 Hz. Secondary feeds a 5 ohm load. Assume ideal. Find (a)  $V_2$ , (b)  $I_2$ , (c)  $I_1$ , (d) P.

(a)  $V_2$

$$V_2 / V_1 = N_2 / N_1 = 100 / 2000 = 1/20$$

$$V_2 = 220 / 20 = 11 \text{ V}$$

(b)  $I_2$

$$I_2 = V_2 / R = 11 / 5 = 2.2 \text{ A}$$

(c)  $I_1$

$$I_1 / I_2 = N_2 / N_1 = 1/20$$

$$I_1 = 2.2 / 20 = 0.11 \text{ A}$$

(d) Power

$$P_{in} = V_1 I_1 = 220 \cdot 0.11 = 24.2 \text{ W}$$

$$P_{out} = V_2 I_2 = 11 \cdot 2.2 = 24.2 \text{ W}$$

$$P_{in} = P_{out} \text{ (ideal, no losses).}$$

Real transformer :  $P_{out} \neq < P_{in}$ ;  $\eta < 1$ .

Typical efficiency 96 % for power-grid units.

## Important Sub - Results

### RMS for non - sinusoidal AC

Square wave :  $I_{rms} = I_0$  . (peak = rms)

Triangular :  $I_{rms} = I_0 / \sqrt{3}$ .

Half sine :  $I_{rms} = I_0 / 2$  .

### Choke coil

An inductor used in AC circuits to limit current without dissipating energy (replaces resistor).

Energy efficient ; used in tube - light starters.

### AC ammeter & voltmeter

Hot - wire type or moving - iron type :

deflection prop to  $I^2$   $\rightarrow$  reads  $I_{rms}$  .

### Phasor algebra cheat

V perpendicular I in pure L or C  $\rightarrow P_{avg} = 0$

V parallel I in pure R  $\rightarrow P_{avg} = V_{rms} I_{rms}$

General :  $P_{avg} = V_{rms} I_{rms} \cos \phi$

### Common pitfalls

- ① Always use rms (not peak) in  $V = IZ$ .
- ② Z is not algebraic sum of  $R + X_L + X_C$ .
- ③ At resonance Z is MIN , I is MAX.
4. Power in pure L or C is zero (wattless).

## AC vs DC - Quick Comparison

### Generation

AC : by rotating a coil in  $B$  (Faraday's law).

DC : by chemical cells, solar cells, rectifiers.

### Transmission

AC : step up by transformer  $\rightarrow$  low  $I$   $\rightarrow$  low  $l_o$

DC : no transformer; HVDC uses costly converters.

### Devices

AC : induction motor, transformer, fan, bulb.

DC : battery, dc motor, electronics (after SMPS).

### Effects

AC : reactance ( $X_L$ ,  $X_C$ ), phase, impedance.

DC : no reactance; only ohmic resistance.

### Safety

AC at same  $V$  is more dangerous (muscle grip).

DC tends to throw the victim off (one twitch).

### Form factor

$$F = I_{rms} / I_{avg} = (I_0 / \sqrt{2}) / (2 I_0 / \pi)$$

$$= \pi / (2 \sqrt{2}) \quad 1.11$$

$$\text{Peak factor} = I_0 / I_{rms} = \sqrt{2} \quad 1.414$$

## Summary - All Key Formulas

### Sinusoidal AC

$$V = V_0 \sin \omega t \quad ; \quad I = I_0 \sin (\omega t - \phi)$$

$$\omega = 2 \pi f \quad ; \quad T = 1 / f$$

### Mean / RMS

$$I_{avg} = 2 I_0 / \pi \quad (\text{half cycle})$$

$$I_{rms} = I_0 / \sqrt{2} \quad ; \quad V_{rms} = V_0 / \sqrt{2}$$

### Reactance & impedance

$$X_L = \omega L \quad ; \quad X_C = 1 / \omega C$$

$$Z = \sqrt{R^2 + (X_L - X_C)^2}$$

$$\tan \phi = (X_L - X_C) / R$$

### Resonance & Q

$$\omega_0 = 1 / \sqrt{LC} \quad ; \quad f_0 = 1 / (2 \pi \sqrt{LC})$$

$$Q = \omega_0 L / R = (1/R) \sqrt{L/C}$$

### Power & power factor

$$P_{avg} = V_{rms} I_{rms} \cos \phi$$

$$\cos \phi = R / Z \quad (\text{power factor})$$

### Transformer

$$V_2 / V_1 = N_2 / N_1 \quad ; \quad I_2 / I_1 = N_1 / N_2$$

$$P_{in} = V_1 I_1 = V_2 I_2 = P_{out} \quad (\text{ideal})$$